

Multilayer approximation of the Navier-Stokes system

Beyond the Saint-Venant system

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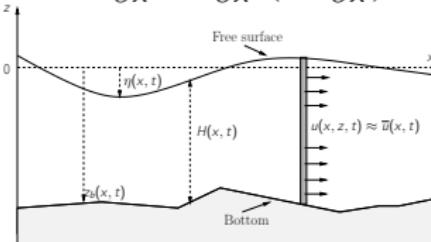
Shallow Water approximation of Navier-Stokes

$$(NS) \left\{ \begin{array}{l} \operatorname{div} \underline{\mathbf{u}} = 0, \\ \dot{\underline{\mathbf{u}}} + (\underline{\mathbf{u}} \cdot \nabla) \underline{\mathbf{u}} + \nabla p = \mathbf{G} + \operatorname{div} \underline{\Sigma}, \end{array} \right.$$

- small parameter $\varepsilon = \frac{H_0}{L_0}$, expansion in $\mathcal{O}(\varepsilon^2)$
- Saint-Venant 1872, Gerbeau 2001, Saleri 2004, Marche 2007
- 2 assumptions : hydrostatic, $u = \bar{u}$

$$(SV) \left\{ \begin{array}{l} \frac{\partial H}{\partial t} + \frac{\partial(H\bar{u})}{\partial x} = 0, \\ \frac{\partial(H\bar{u})}{\partial t} + \frac{\partial}{\partial x} \left(H\bar{u}^2 + \frac{g}{2}H^2 \right) = -gH \frac{\partial z_b}{\partial x} + \frac{\partial}{\partial x} \left(4\mu \frac{\partial \bar{u}}{\partial x} \right) - \kappa(\bar{u}) \end{array} \right.$$

- Reduced complexity
- Many applications
- Hyperbolic CL



NOTATIONS: free surface η , bottom z_b , water height $H = \eta - z_b$, velocities $\underline{\mathbf{u}} = (u, w)$, $\bar{u}(x, t) = \frac{1}{H} \int_{z_b}^{\eta} u(x, z, t) dz$

Navier-Stokes vs. Saint-Venant

2D Navier-Stokes $H, \mathbf{u} = (u, w)$

$$\begin{cases} \operatorname{div} \underline{\mathbf{u}} = 0, \\ \dot{\underline{\mathbf{u}}} + (\underline{\mathbf{u}} \cdot \nabla) \underline{\mathbf{u}} + \nabla p = \mathbf{G} + \operatorname{div} \underline{\underline{\Sigma}}, \end{cases}$$

Saint-Venant H, \bar{u}

$$\begin{cases} \frac{\partial H}{\partial t} + \frac{\partial(H\bar{u})}{\partial x} = 0, \\ \frac{\partial(H\bar{u})}{\partial t} + \frac{\partial}{\partial x} \left(H\bar{u}^2 + \frac{g}{2}H^2 \right) = -gH \frac{\partial z_b}{\partial x} - \kappa(\bar{u}) \end{cases}$$

Complexity of Navier-Stokes

- functional analysis
- numerical schemes
- geometrical models
- computational costs and use

Advantages of Saint-Venant

- fixed meshes
- reduced computational costs
- efficient numerical methods (finite volumes)

Main ideas & Outline

- The Saint-Venant system is widely used
but too simple for complex flows
Various approximations of Navier-Stokes
with a Saint-Venant-like approach
- Importance of the discretization, especially for the source terms
Advantages of the kinetic description

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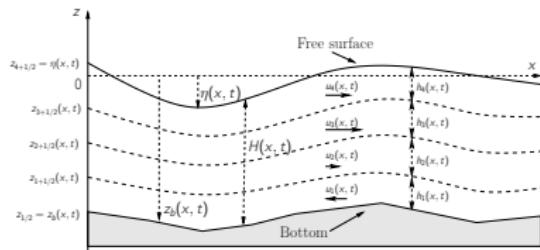
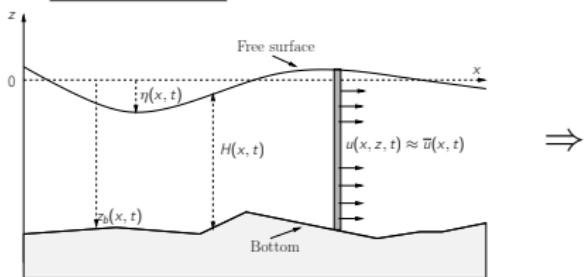
Models

Kinetic descriptions & Numerical schemes

Numerical validations & simulations

1.1 Beyond the Saint-Venant system

Objective



- Many contributions (Audusse, Bouchut, LeVeque, Pares, ...)
- Valid for non-miscible fluids
- Pb. with underlying physics,...

Key idea

Saint-Venant

$$u(x, z, t) \approx \bar{u}(x, t)$$



Multilayer Saint-Venant

$$u(x, z, t) \approx \sum_{\alpha=1}^N \mathbb{I}_{z \in L_\alpha(x, t)} u_\alpha(x, t)$$

1.1 Model derivation

Starting point

$$\text{(Euler hydro)} \quad \left\{ \begin{array}{l} \frac{\partial u}{\partial x} + \frac{\partial w}{\partial z} = 0 \\ \frac{\partial u}{\partial t} + \frac{\partial u^2}{\partial x} + \frac{\partial uw}{\partial z} + \frac{\partial p}{\partial x} = 0 \\ \frac{\partial p}{\partial z} = -g \end{array} \right.$$

Obtained model

- Weak form (\mathbb{P}_0^t) of the continuity equation

with $\mathbb{P}_0^t = \{\mathbb{I}_{z \in L_\alpha(x,t)}, 1 \leq \alpha \leq N\}$

$$\frac{\partial h_\alpha}{\partial t} + \frac{\partial h_\alpha u_\alpha}{\partial x} = G_{\alpha+1/2} - G_{\alpha-1/2}$$

$$G_{\alpha+1/2} = \frac{\partial z_{\alpha+1/2}}{\partial t} + u_{\alpha+1/2} \frac{\partial z_{\alpha+1/2}}{\partial x} - w_{\alpha+1/2}$$

$G_{1/2} = G_{N+1/2} = 0$ (kinematic boundary conditions)

1.1 Model derivation

Starting point

$$\text{(Euler hydro)} \quad \left\{ \begin{array}{l} \frac{\partial u}{\partial x} + \frac{\partial w}{\partial z} = 0 \\ \frac{\partial u}{\partial t} + \frac{\partial u^2}{\partial x} + \frac{\partial uw}{\partial z} + \frac{\partial p}{\partial x} = 0 \\ \frac{\partial p}{\partial z} = -g \end{array} \right.$$

Obtained model

- Weak form (\mathbb{P}_0^t) of the Euler system $\mathbb{P}_0^t = \{\mathbb{I}_{z \in L_\alpha(x,t)}, 1 \leq \alpha \leq N\}$

$$\left\{ \begin{array}{l} \frac{\partial H}{\partial t} + \sum_{\alpha=1}^N \frac{\partial}{\partial x}(h_\alpha u_\alpha) = 0 \\ \frac{\partial(h_\alpha u_\alpha)}{\partial t} + \frac{\partial}{\partial x} \left(h_\alpha u_\alpha^2 + \frac{g}{2} h_\alpha f(\{h_j\}_{j \geq \alpha}) \right) = F_{\alpha+1/2} - F_{\alpha-1/2} \\ \frac{\partial E_\alpha}{\partial t} + \frac{\partial}{\partial x} \left(u_\alpha \left(E_\alpha + \frac{g}{2} h_\alpha H \right) \right) = E_{\alpha+1/2} - E_{\alpha-1/2} \end{array} \right.$$

- Only one “global” continuity equation, $H = \sum h_\alpha$
- Exchange terms $G_{\alpha+1/2}$, $F_{\alpha+1/2} = u_{\alpha+1/2} G_{\alpha+1/2} + P_{\alpha+1/2}$,
- $E_{\alpha+1/2} = \frac{u_{\alpha+1/2}^2}{2} G_{\alpha+1/2} + u_{\alpha+1/2} P_{\alpha+1/2}$
- If $G_{\alpha+1/2} \equiv 0$ non-miscible fluids, N cont. equations

1.2 Properties of the model

- **Hyperbolicity ?**

quasi-linear form $X = (H, u_1, \dots, u_N, E_1, \dots, E_N)^T$

$$M(X)\dot{X} + F(X)\frac{\partial X}{\partial x} = 0$$

- “often” hyperbolic
- strictly hyperbolic for $N = 2$
- for $N > 2$, “arrow matrices” and interlacing of eigenvalues

$$\frac{1}{N} \sum_1^N u_i^2 \leq gH \quad (\textit{generalized Froude number})$$

- family of entropies
- More complex approximation

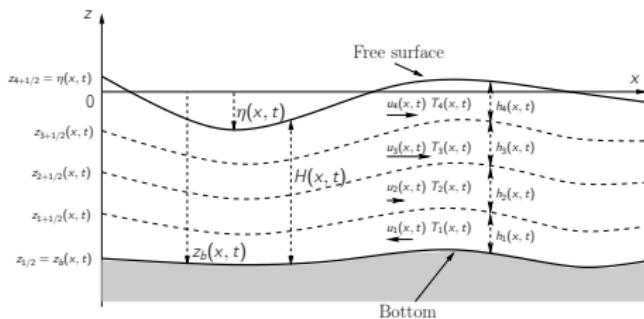
$$u(x, z, t) \approx \sum_{\alpha=1}^N P_\alpha(z) u_\alpha(x, t), \quad \text{with} \quad \deg(P_\alpha) = k$$

Hydrostatic Euler (NS) with varying density (Aud., Brist., JSM, JCP 2010)

Starting point

$$\left\{ \begin{array}{l} \dot{\rho} + \operatorname{div}(\rho \underline{\mathbf{u}}) = 0, \\ \dot{\rho \underline{\mathbf{u}}} + (\underline{\mathbf{u}} \cdot \nabla)(\rho \underline{\mathbf{u}}) + \nabla p = \rho \mathbf{G}, \\ \dot{\rho T} + \operatorname{div}(\rho T \underline{\mathbf{u}}) = \mu_T \Delta T, \end{array} \right.$$

with $\rho = \rho(\{T, S\})$ ($= \rho(T, S, H)$)



Obtained model

$$u(x, z, t) \approx \sum_{\alpha=1}^N \mathbb{I}_{z \in L_\alpha} u_\alpha(x, t)$$

$$\left\{ \begin{array}{l} \frac{\partial}{\partial t} \sum_{\alpha=1}^N (\rho_\alpha h_\alpha) + \sum_{\alpha=1}^N \frac{\partial}{\partial x} (\rho_\alpha h_\alpha u_\alpha) = 0, \\ \frac{\partial(\rho_\alpha h_\alpha u_\alpha)}{\partial t} + \frac{\partial}{\partial x} \left(\rho_\alpha h_\alpha u_\alpha^2 + \frac{g}{2} h_\alpha f(\{\rho_j h_j\}_{j \geq \alpha}) \right) = \\ \quad + u_{\alpha+1/2} G_{\alpha+1/2} - u_{\alpha-1/2} G_{\alpha-1/2} + \textcolor{red}{Sc. Terms}, \\ \frac{\partial(\rho_\alpha h_\alpha T_\alpha)}{\partial t} + \frac{\partial}{\partial x} (\rho_\alpha h_\alpha u_\alpha T_\alpha) = T_{\alpha+1/2} G_{\alpha+1/2} - T_{\alpha-1/2} G_{\alpha-1/2}, \end{array} \right.$$

What to do with such models ?

- A family of models between Saint-Venant and Navier-Stokes
- Also other models (non-hydrostatic Saint-Venant system, section-averaged)
- Good candidates
 - rigourous derivation process
 - energy balance, entropies
- Simpler than the corresponding Navier-Stokes system
 - independant of z , **fixed meshes**
- But not so simple to analyse & discretize !

Kinetic approach for conservation laws

- A fantastic tool for
 - physical understanding
 - mathematical analysis
 - numerical analysis and schemes
- Basis : adopt a microscopic description (Boltzmann)

$$\text{Cont. model} \Leftrightarrow \frac{\partial M}{\partial t} + \xi \frac{\partial M}{\partial x} - g \frac{\partial z_b}{\partial x} \frac{\partial M}{\partial \xi} = Q(x, t, \xi)$$

- $M(x, t, \xi)$ particle density, $Q(x, t, \xi)$ collision term ($= 0$ a.e.)
- $\int_{\mathbb{R}} \xi^p M d\xi$ gives the macroscopic variables
- linear transport equation + Vlasov
- Only kinetic representations and not kinetic formulations

Kinetic representation of the Saint-Venant system

- Gibbs equilibrium $M(x, t, \xi) = \frac{H}{c} \chi\left(\frac{\xi - \bar{u}}{c}\right)$ with $c = \sqrt{gH/2}$
 where $\chi(\omega) = \chi(-\omega) \geq 0$, $\text{supp } (\chi) \subset \Omega$, $\int_{\mathbb{R}} \chi(\omega) = \int_{\mathbb{R}} \omega^2 \chi(\omega) = 1$

Proposition (Audusse, Bristeau, Perthame 2004)

The functions $(H, \bar{u}, E)(t, x)$ are strong solutions of the Saint-Venant system if and only if $M(x, t, \xi)$ is solution of the kinetic equation

$$(\mathcal{B}), \quad \frac{\partial M}{\partial t} + \xi \frac{\partial M}{\partial x} - g \frac{\partial z_b}{\partial x} \frac{\partial M}{\partial \xi} = Q(x, t, \xi)$$

where $Q(t, x, \xi)$ is a “collision term”.

- Macroscopic variables $(H, \bar{u}, E) = \int_{\mathbb{R}} (1, \xi, \xi^2/2) M \, d\xi$
- A linear transport equation . . . easy to upwind

Kinetic interpretation for the multilayer system

- Gibbs equilibria

- $M_\alpha(x, t, \xi) = \frac{h_\alpha}{c_\alpha} \chi\left(\frac{\xi - u_\alpha}{c_\alpha}\right), \quad \text{with } c_\alpha = \sqrt{gf(\{h_j\}_{j \geq \alpha})}$
- $N_{\alpha+1/2}(x, t, \xi) = G_{\alpha+1/2} \delta(\xi - u_{\alpha+1/2}),$

Proposition (Audusse, Bristeau, Perthame, JSM 2009)

The functions $(h_\alpha, u_\alpha, E_\alpha)(t, x)$ are strong solutions of the multilayer Saint-Venant system if and only if the set $\{M_j(x, t, \xi)\}_{j=1}^N$ is solution of the kinetic equations

$$\frac{\partial M_\alpha}{\partial t} + \xi \frac{\partial M_\alpha}{\partial x} - N_{\alpha+1/2} + N_{\alpha-1/2} = Q_\alpha(x, t, \xi)$$

- source terms (exchanges, pressure)
- also for variable density case

Main properties of the schemes

- $f_i^{n+1}(\xi) = M_i^n(\xi) - \xi \sigma_i^n \left(M_{i+1/2}^n(\xi) - M_{i-1/2}^n(\xi) \right) + \Delta t^n S_i^n(\xi)$
- Positive schemes (CFL=1 but more complex)
- 2nd order schemes (space & time)
- Well balanced (with hydrostatic reconstruction)
- (Discrete entropy)
- Maximum principle (tracer)
- The source terms (pressure)

$$gH \frac{\partial z_b}{\partial x} \Rightarrow g \frac{\partial z_b}{\partial x} \frac{\partial M}{\partial \xi}$$

- kinetic interpretation useful for discretization
- Numerical cost $\mathcal{O}(N \times 1)$, possibly mesh adaptation

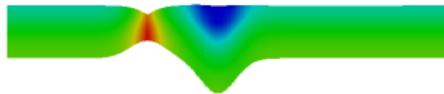
Analytical validation (I) (Boulanger, JSM 2011)

- Analytical solutions to the Euler system
 - 2D and 3D solutions, for any bottom topography $z_b(x, y)$
 - with entropic shocks
 - limit of Navier-Stokes solutions at vanishing viscosity
 - not necessarily free surface flows
 - In 2D (continuous solutions), u and H characterized by

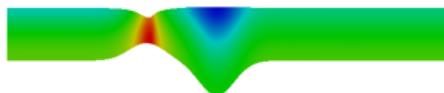
$$u = \alpha\beta \frac{\cos \beta(z - z_b)}{\sin \beta H}, \quad \left[\frac{gH^2}{2} + \frac{\alpha^2 \beta^2 H}{2 \sin(\beta H)^2} + \frac{\alpha^2 \beta \cos(\beta H)}{2 \sin(\beta H)} \right] = 0$$

- Recovered by the 2D and 3D codes

- analytic

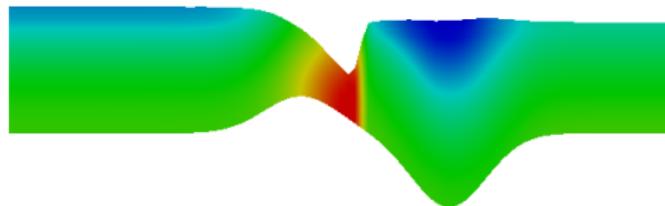
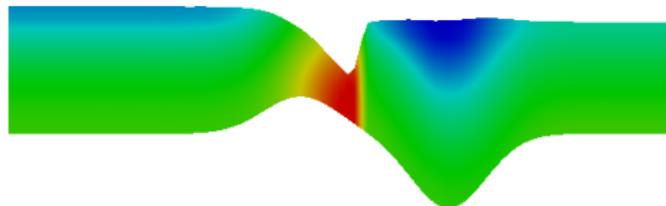


- simulated



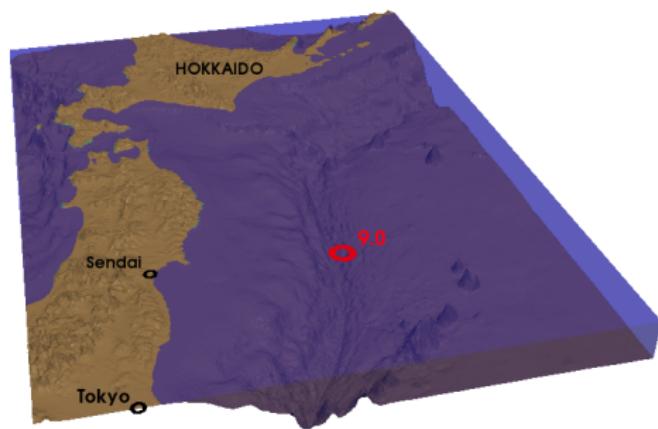
Analytical validation (II)

- With shocks

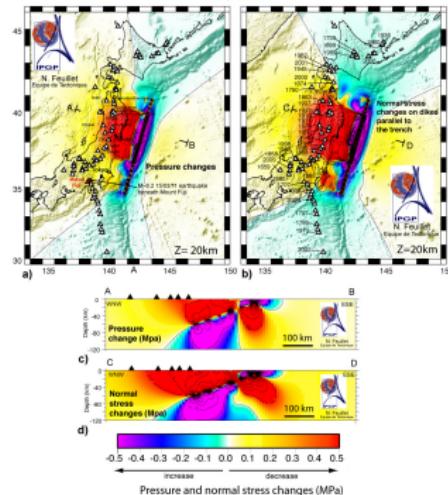


- Also without free surface

Honshu seismic



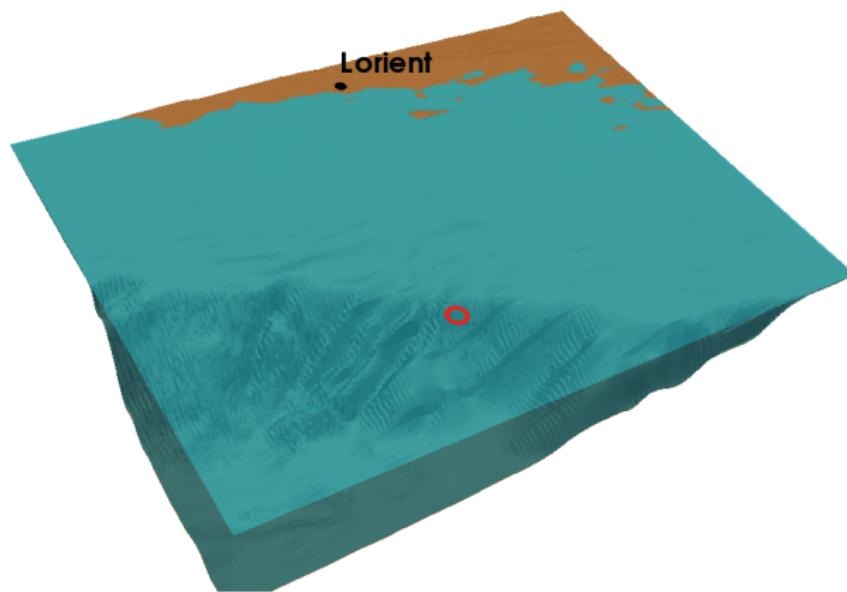
Pressure and normal stress changes induced by the M=9 March 11 2011 Sendai earthquake
Nathalie Feuillet, Institut de Physique du Globe de Paris, France
March, 15 2011



seism

source IPGP (A. Mangeney)

The next tsunami : Guidel 6.0 !



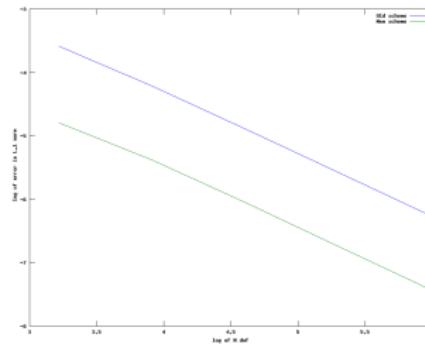
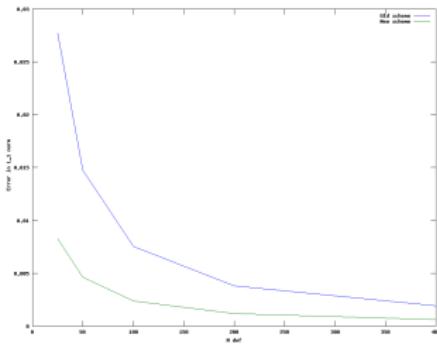
seism

New scheme without hydrostatic reconstruction

- Well balanced scheme using discretization of the Vlasov term

$$\frac{\partial M}{\partial t} + \xi \frac{\partial M}{\partial x} - g \frac{\partial z_b}{\partial x} \frac{\partial M}{\partial \xi} = Q(x, t, \xi)$$

- Convergence test



For the future

➡ Numerical analysis & schemes

- for the full NS system
- hyperbolicity, entropies, . . .
- stability of the schemes
- towards industrial codes

➡ Interaction with structures

- erosion, carriage and associated problems
- CEMRACS 2011

➡ Hydrodynamics-biology coupling

- water quality management

➡ Control, data assimilation, . . .

- everything is more simple at the kinetic level