



Isogeometric Residual Distribution Scheme

Algiane Froehly

Rémi Abgrall

Cécile Dobrzynski





Introduction

Theoretical Framework

Euler Equations

Residual Distribution Schemes (\mathcal{RDS})

\mathcal{RDS} with \mathcal{NURBS}

\mathcal{NURBS} Generalities

Residuals Computation

\mathcal{NURBS} Mesh generation

Numerical Results



Introduction

Theoretical Framework

\mathcal{RDS} with \mathcal{NURBS}

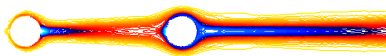
\mathcal{NURBS} Mesh generation

Numerical Results



Introduction

Problematic



Subsonic flow around 2 cylindres: spurious entropy production

Solution

Isogeometric analysis



Introduction

Theoretical Framework

Euler Equations

Residual Distribution Schemes (\mathcal{RDS})

\mathcal{RDS} with \mathcal{NURBS}

\mathcal{NURBS} Mesh generation

Numerical Results



Euler Equations

Conservative form

$$\mathbf{U} = \begin{pmatrix} \rho \\ \rho \vec{\mathbf{u}} \\ \rho E \end{pmatrix}, \begin{cases} \vec{\nabla} \cdot [\rho \vec{\mathbf{u}}] & = 0 & \text{Conservation of mass} \\ \vec{\nabla} \cdot [\rho u_i \vec{\mathbf{u}} + p \delta_i] & = 0 & \text{Conservation of momentum} \\ \vec{\nabla} \cdot [(\rho E + p) \vec{\mathbf{u}}] & = 0 & \text{Conservation of Energy} \end{cases}$$



Euler Equations

Conservative form

$$\mathbf{U} = \begin{pmatrix} \rho \\ \rho \vec{\mathbf{u}} \\ \rho E \end{pmatrix}, \begin{cases} \vec{\nabla} \cdot [\rho \vec{\mathbf{u}}] & = 0 & \text{Conservation of mass} \\ \vec{\nabla} \cdot [\rho u_i \vec{\mathbf{u}} + p \delta_i] & = 0 & \text{Conservation of momentum} \\ \vec{\nabla} \cdot [(\rho E + p) \vec{\mathbf{u}}] & = 0 & \text{Conservation of Energy} \end{cases}$$

Problem to solve

$$\begin{cases} \vec{\nabla} \cdot \vec{\mathcal{F}}(\mathbf{U}) = 0 & \forall x \in \Omega \\ \text{weak boundary conditions} & (BC) \end{cases}$$



\mathcal{RDS}

Definitions

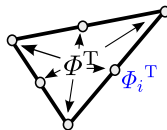
- Φ^T : total residual over T

$$\Phi^T = \int_{\partial T} \vec{\mathcal{F}}(\mathbf{U}^h) \cdot \vec{\mathbf{n}} d\partial T$$

- Φ_i^T : local nodal residual

$$\sum_{i \in T} \Phi_i^T = \Phi^T$$

$$\Phi_i^T = \text{High-order term} + \text{Stabilization term}$$



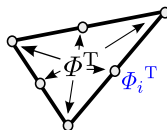


RDS

Definitions

- Φ^T : total residual over T

$$\Phi^T = \int_{\partial T} \vec{\mathcal{F}}(\mathbf{U}^h) \cdot \vec{\mathbf{n}} d\partial T$$



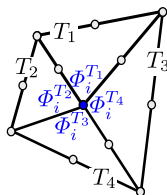
- Φ_i^T : local nodal residual

$$\sum_{i \in T} \Phi_i^T = \Phi^T$$

$$\Phi_i^T = \text{High-order term} + \text{Stabilization term}$$

RDS formulation

$$\forall M_i, \sum_{T \ni M_i} \Phi_i^T(\mathbf{U}^h) = 0$$





Introduction

Theoretical Framework

\mathcal{RDS} with \mathcal{NURBS}

\mathcal{NURBS} Generalities

Residuals Computation

\mathcal{NURBS} Mesh generation

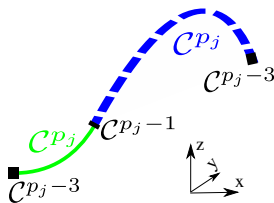
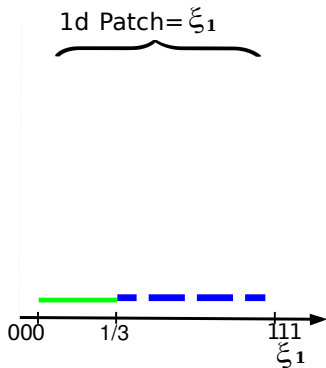
Numerical Results



Non Uniform Rational B-Spline Definitions

B-Splines basis functions in \mathbb{R}^d defined by :

- their polynomial order in the j^{th} dimension: p_j
- d knot vectors $(\xi_j)_{j=1,d}$

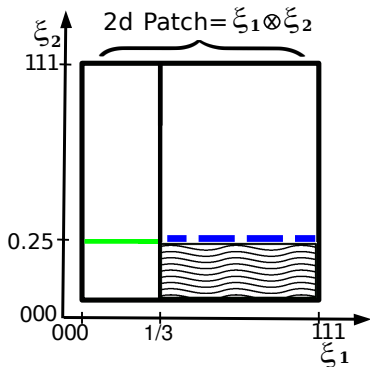




Non Uniform Rational B-Spline Definitions

B-Splines basis functions in \mathbb{R}^d defined by :

- their polynomial order in the j^{th} dimension: p_j
- d knot vectors $(\xi_j)_{j=1,d}$





Non Uniform Rational B-Spline Definitions

B-Splines basis functions in \mathbb{R}^d defined by :

- their polynomial order in the j^{th} dimension: p_j
- d knot vectors $(\xi_j)_{j=1,d}$

NURBS basis functions in \mathbb{R}^d defined by :

- The n_j B-Splines basis functions in the j^{th} dimension
- A set of n_j weighting factors: W_l

B-Splines and NURBS basis functions for $d = 1$

i^{th} NURBS function of order k :

$$M_{i,k}(\xi) = \frac{W_i N_{i,k}(\xi)}{\sum_{l=1,n} W_l N_{l,k}(\xi)}$$

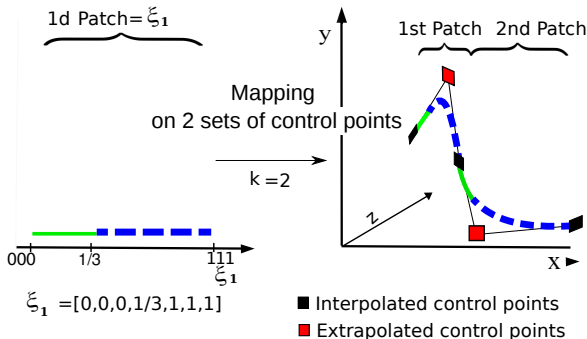


Non Uniform Rational B-Spline Definitions

NURBS curves and surfaces extrapolation

$$C(\xi) = \sum_{i=1, n} \tilde{P}_i M_{i, k}(\xi); \quad S(\xi, \eta) = \sum_{i=1, n \times m} \tilde{P}_i \Psi_{i, k}(\xi, \eta)$$

Mapping NURBS





\mathcal{NURBS} adaptation for \mathcal{RDS}

Numerical simplifications and basis functions used

- Same nodal vector for all edges: $\xi = \overbrace{[0, 0, \dots, \dots]}^{k \text{ times}}, \overbrace{[\dots, 1, 1]}^{k \text{ times}}$
- One unique weight per point
- Definition of B-Spline-like basis for triangular elements :

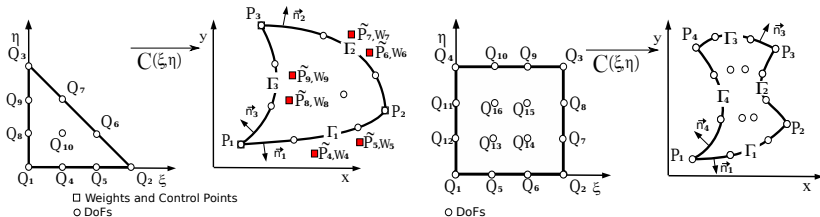
$$\binom{k}{j_1, j_2, j_3} \xi^{j_1} \eta^{j_2} \zeta^{j_3}, \quad j \in [|1, k|], \quad j_1 + j_2 + j_3 = k$$



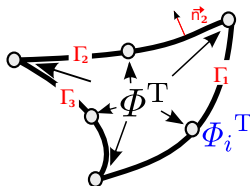
$NURBS$ adaptation for \mathcal{RDS}

Numerical simplifications and basis functions used

- Same nodal vector for all edges: $\xi = \overbrace{[0, 0, \dots, \dots]}^{k \text{ times}}, \overbrace{[\dots, 1, 1]}^{k \text{ times}}$
- One unique weight per point
- Definition of B-Spline-like basis for triangular elements



Residuals computation



Total residual computation

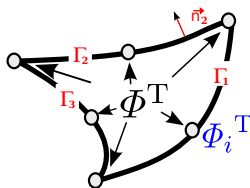
$$\Phi^T = \int_{\partial T} \vec{\mathcal{F}}_h \cdot \vec{n} d\partial T = \sum_{j=1, n_e} \int_{\Gamma_j} \left(\sum_{l=1}^{n_{\text{DoFs}}} \vec{\mathcal{F}}_l \psi_l(\xi, \eta) \right) \cdot \vec{n}_j(x, y) d\Gamma_j$$

3-points Gauss-Legendre quadrature at order 3

6-points Gauss-Legendre quadrature at order 4



Residuals computation



Stabilization term computation

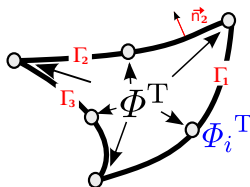
$$D_i^T = \int_T (\vec{\lambda} \cdot \overrightarrow{\nabla \Psi_i}) \bar{\tau} (\vec{\lambda} \cdot \overrightarrow{\nabla \mathbf{U}_h}) dT$$

7-points Gauss-Legendre quadrature at order 3

13-points Gauss-Legendre quadrature at order 4



Slip wall Boundary Condition: $\vec{\mathbf{u}} \cdot \vec{\mathbf{n}} = \vec{\mathbf{0}}$



Weak formulation at the i^{th} boundary node

$$\Phi_{b,i,\Gamma} = \int_{\Gamma} \psi_i^T \vec{\mathcal{F}}_{\text{slip}}(\mathbf{U}_h^n, \vec{\mathbf{n}}) d\Gamma$$

$$\Phi_{b,i,\Gamma} = \sum_{q=1}^{n_{\text{quad}}} \left(\tilde{\omega}_q \psi_i^T(\xi_q) \vec{\mathcal{F}}_{\text{slip}}(\mathbf{U}_h^n(\xi_q), \vec{\mathbf{n}}(\xi_q)) \|\Gamma\| \right)$$

$(k-1)^2$ -points Newton-Cotes quadrature at order k



Introduction

Theoretical Framework

\mathcal{RDS} with \mathcal{NURBS}

\mathcal{NURBS} Mesh generation

Numerical Results



$NURBS$ Mesh generation

Problematic

- $NURBS$ mesh needed to use isogeometric analysis

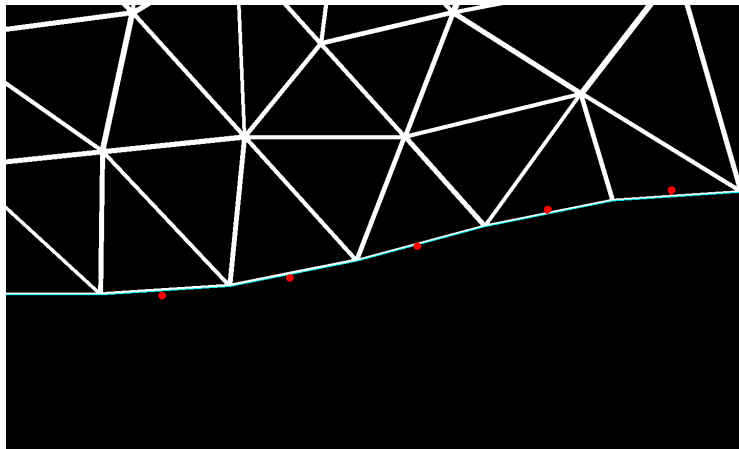
Solution

- Classical meshing of the geometry (piecewise linear)
- Computing the control points and weights needed to extrapolate a $NURBS$ curve verifying that :
 - \mathcal{G}_0 continuity is preserved (the curve interpolate each $P1$ point)
 - Each boundary edge is approached by a portion of circle



\mathcal{NURBS} Mesh generation

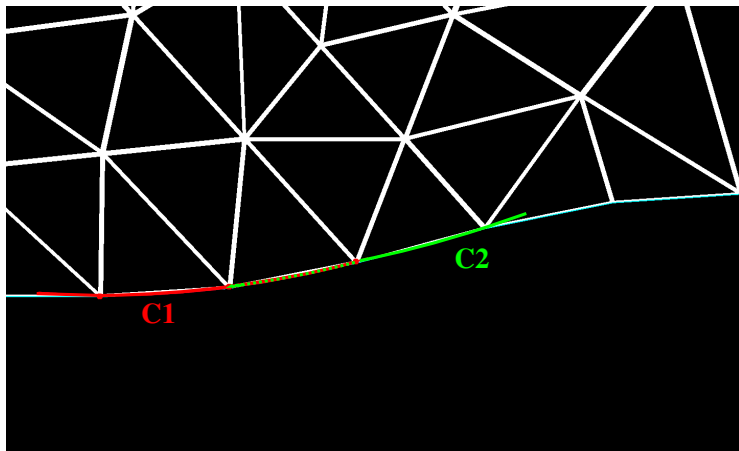
From classical mesh to \mathcal{NURBS} mesh





$NURBS$ Mesh generation

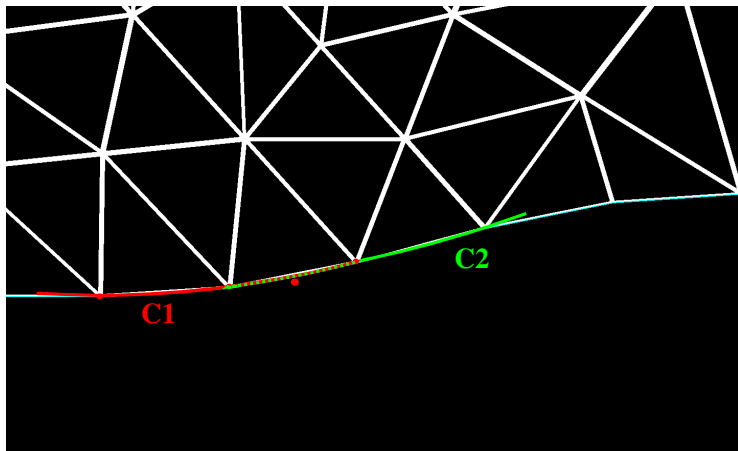
From classical mesh to $NURBS$ mesh





$NURBS$ Mesh generation

From classical mesh to $NURBS$ mesh





Introduction

Theoretical Framework

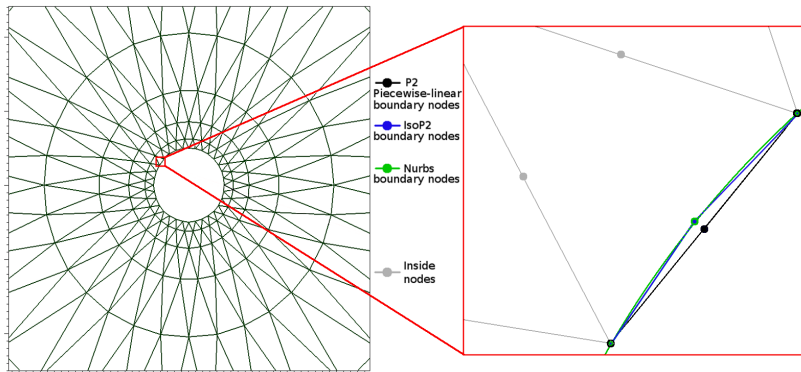
\mathcal{RDS} with \mathcal{NURBS}

\mathcal{NURBS} Mesh generation

Numerical Results

Subsonic flow around a cylinder: $Ma = 0.38$

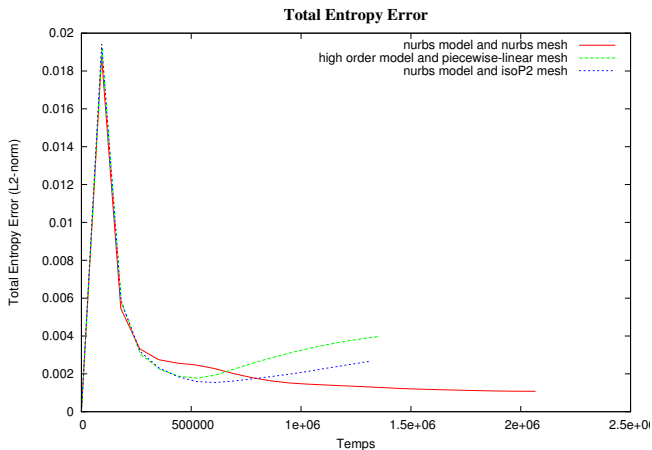
Boundaries representation



P2 picewise-linear mesh, IsoP2 mesh and Nurbs mesh



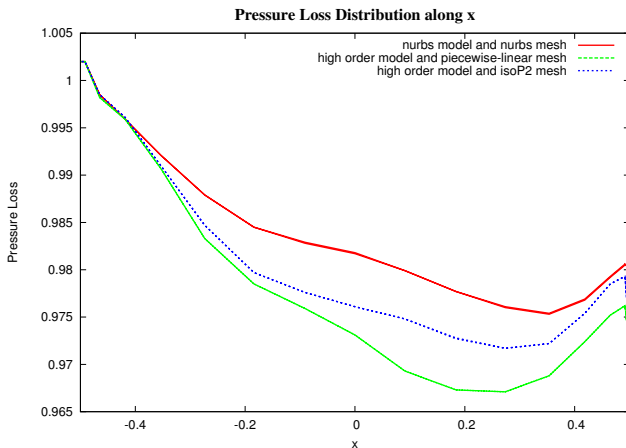
Subsonic flow around a cylinder: $Ma = 0.38$



L2-entropy error during iterations for 8×32 nodes meshes



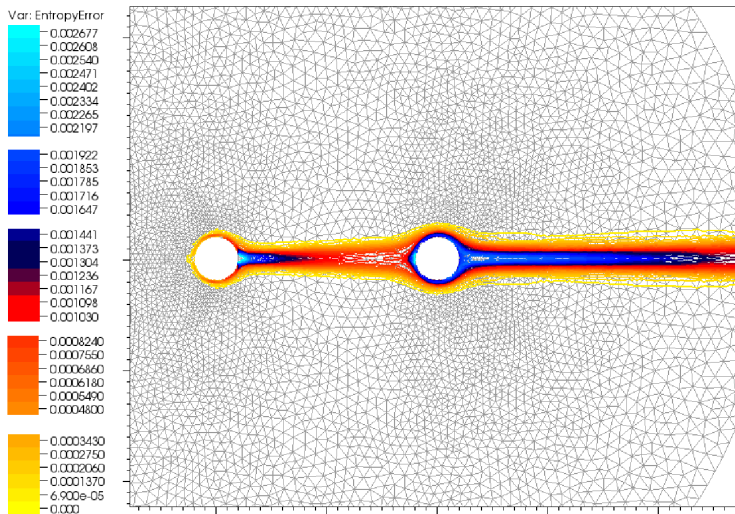
Subsonic flow around a cylinder: $Ma = 0.38$



Pressure loss distribution along cylinder for 8×32 nodes meshes



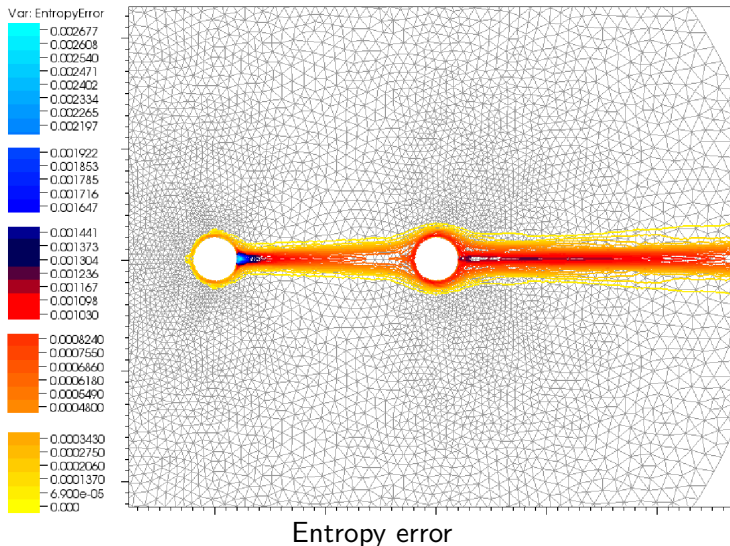
Subsonic flow around 2 cylindres: $Ma = 0.38$



Entropy error

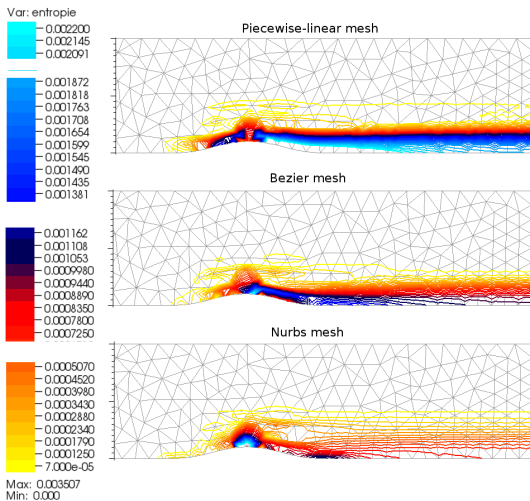


Subsonic flow around 2 cylindres: $Ma = 0.38$





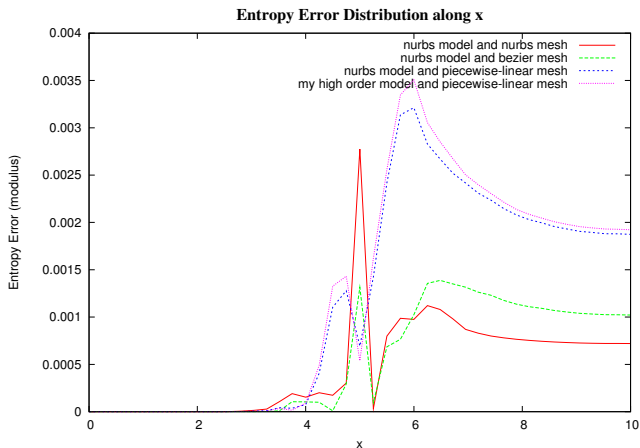
Subsonic flow over a bump: $Ma = 0.63$, slope=26%



Entropy error on the whole bump meshes



Subsonic flow over a bump: $Ma = 0.63$, slope=26%



L2-Entropy error along the bump floor



Conclusion

Done work

- \mathcal{RDS} Isogeometric of order 3 and 4 for triangular, quadrangular and hybrid 2D-meshes
- \mathcal{RDS} Isogeometric of order 3 for tetrahedral 3D-mesh
- Automatic generation of 2D $NURBS$ meshes

Perspectives

- To adapt Isogeometric analysis to Navier-Stokes equations
- Automatic generation of 3D $NURBS$ meshes