# Numerical approximation of non classical solutions of Riemann problems

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#### Introduction

Hyperbolic system of conservation laws (in 1D):

$$\partial_t \mathbf{u}(x,t) + \partial_x \mathbf{f}(\mathbf{u}(x,t)) = 0, \qquad x \in \mathbb{R}, \ t > 0,$$
  
$$\mathbf{u}(x,0) = \mathbf{u}_0(x), \qquad x \in \mathbb{R},$$

with  $\mathbf{u}: \mathbb{R} \times \mathbb{R}^+ \to \mathbb{R}^d$  vector of state quantities and  $\mathbf{f}: \mathbb{R}^d \to \mathbb{R}^d$  given flux function.

Some examples:

- linear transport equation:  $\partial_t \rho(x,t) + a(x,t)\partial_x \rho(x,t) = 0$ ,
- Burgers equation:  $\partial_t u(x,t) + u(x,t)\partial_x u(x,t) = 0$ ,
- Euler equations in fluid dynamics, etc.

## From PDE to ODE Application to a scalar problem Application to a *p*-system problem

- Existence of smooth solutions in short time.
- Nonlinearity and long time  $\Rightarrow$  lost of smoothness.
- Work with weak solutions... Not unique! Impose an entropy criterion to select one admissible solution (a physical one).

#### Some references:

- Godlewski, Raviart, Hyperbolic Systems of Conservation Laws (1991)
- Leveque, Numerical Methods for Conservation Laws (1992)
- Serre, Systèmes de lois de conservation, tomes 1, 2 (1996)

## Classical numerical approach: Finite Volumes

- Consider a bounded domain  $[x_{min}, x_{max}]$  and add boundary conditions.
- Introduce mesh points  $x_i = x_{min} + i\Delta x$  and consider approximation at time  $t^n = n\Delta t$  given by

$$\mathbf{u}_i^n \approx \frac{1}{\Delta x} \int_{x_i - \Delta x/2}^{x_i + \Delta x/2} \mathbf{u}(t^n, x) dx.$$

• From time  $t^n$  to time  $t^{n+1}$ , solve on each cell a Riemann problem

$$\partial_t \mathbf{u} + \partial_x \mathbf{f}(\mathbf{u}) = 0, \qquad t \in [t^n, t^{n+1}],$$

$$\mathbf{u}(x, t^n) = \begin{cases} \mathbf{u}_i^n & \text{if } x < x_i + \Delta x/2, \\ \mathbf{u}_{i+1}^n & \text{if } x > x_i + \Delta x/2. \end{cases}$$

• Construct schemes by defining approximations of flux derivative.

## Our objective

 Approximate the Riemann solutions of systems of conservation laws in the form:

$$\partial_t \mathbf{u} + \partial_x \mathbf{f}(\mathbf{u}) = 0, \qquad x \in \mathbb{R}, \ t > 0,$$
 (1)

completed with an initial data given by

$$\mathbf{u}(x,0) = \begin{cases} \mathbf{u}_L & \text{if } x < 0, \\ \mathbf{u}_R & \text{if } x > 0, \end{cases}$$
 (2)

where

- $\mathbf{u}_L$  and  $\mathbf{u}_R$  are two given constant states in  $\Omega \subset \mathbb{R}^d$ ,
- $\mathbf{u}(x,t) \in \Omega$  is the unknown state vector,
- $\mathbf{f}: \Omega \to \mathbb{R}^d$  is a given smooth flux function.
- Contrary to the usual approach, we do not enforce entropy criterion, so that we will be able to see non classical solutions.

### Non classical solutions?

- In the scalar classical case (i.e. with entropy criterion):
  - if f is convex (or concave): solution of Riemann problem (1)-(2) is a shock, or a rarefaction wave,
  - if f is neither convex nor concave: we may have a composite wave (two appended waves).
- Here, we are interested in solutions that violate entropy conditions: non classical solutions composed of two separated waves.

### Outline

- 1 From PDE to ODE
- 2 Application to a scalar problem
- $\odot$  Application to a p-system problem

## $\begin{array}{c} \textbf{From PDE to ODE} \\ \textbf{Application to a scalar problem} \\ \textbf{Application to a } p\text{-system problem} \end{array}$

- 1 From PDE to ODE
- 2 Application to a scalar problem
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## Diffusive-dispersive system of conservation laws

• Solution  $\mathbf{u} \in \Omega$  assumed to be the limit solution [see 4], when  $\varepsilon \to 0$ , of

$$\partial_t \mathbf{u}^{\varepsilon} + \partial_x \mathbf{f}(\mathbf{u}^{\varepsilon}) = \varepsilon \beta \partial_{xx} \mathbf{D}(\mathbf{u}^{\varepsilon}) + \varepsilon^2 \gamma \partial_{xxx} \mathbf{D}(\mathbf{u}^{\varepsilon}), \quad (3)$$

with  $\mathbf{D}: \Omega \to \mathbb{R}^d$  a given smooth function.

- Competition between diffusion that makes the solution smoother and dispersion that creates oscillations.
- Solutions  $\mathbf{u}^{\varepsilon}$  of (3) may depend on the ratio  $\beta/\gamma$  [see 5].
- If f is neither convex nor concave: waves may be separated, solutions may be non classical.

<sup>&</sup>lt;sup>4</sup>LeFloch, Rohde 2001 (IUMJ)

<sup>&</sup>lt;sup>5</sup>LeFloch 2002 (Book)

## Dafermos viscosity approach

- Riemann solutions **u** of (1)-(2) are self-similar: only depend on the variable  $\xi = x/t$ .
- Solutions  $\mathbf{u}^{\varepsilon}$  of diffusive-dispersive problem (3) are not self-similar.
- Reformulation of the diffusive-dispersive system according to the Dafermos viscosity approach [see 6]:

$$\partial_t \mathbf{u}^{\varepsilon} + \partial_x \mathbf{f}(\mathbf{u}^{\varepsilon}) = \varepsilon t \beta \partial_{xx} \mathbf{D}(\mathbf{u}^{\varepsilon}) + \varepsilon^2 t^2 \gamma \partial_{xxx} \mathbf{D}(\mathbf{u}^{\varepsilon}).$$

<sup>&</sup>lt;sup>6</sup>Dafermos 2010 (Book)

## ODE problem

• Change of variables given by

$$\mathbf{u}^{\varepsilon}(x,t) = \mathbf{u}(\xi)$$
 with  $\xi = \frac{x}{t}$ .

ODE system

$$-\xi \mathbf{u}' + \mathbf{f}(\mathbf{u})' = \varepsilon \beta \mathbf{D}(\mathbf{u})'' + \varepsilon^2 \gamma \mathbf{D}(\mathbf{u})'''.$$

• Limit boundary conditions

$$\lim_{\xi \to -\infty} \mathbf{u}(\xi) = \mathbf{u}_L \quad \text{ and } \quad \lim_{\xi \to +\infty} \mathbf{u}(\xi) = \mathbf{u}_R$$

replaced by

$$\mathbf{u}(-\ell) = \mathbf{u}_L$$
 and  $\mathbf{u}(\ell) = \mathbf{u}_R$ ,

with  $\ell > 0$  large enough [see 7].

<sup>&</sup>lt;sup>7</sup>Joseph, LeFloch 2007 (P ROY SOC EDINB A)

### Numerical method

- 4th order Finite Difference scheme (N mesh points).
- For fixed  $\varepsilon > 0$ : existence of the discrete solution is proven.
- For fixed  $\varepsilon > 0$ : solving the nonlinear system in  $\mathbb{R}^N$  with a Newton method.
- Decrease  $\varepsilon$  to approach the limit solution and use the solution given by a higher  $\varepsilon$  as initial guess to make the convergence of the Newton method easier.

## From PDE to ODE Application to a scalar problem Application to a p-system problem

- From PDE to ODE
- 2 Application to a scalar problem
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#### From scalar conservation law to ODE

• Diffusive-dispersive scalar equation

$$\partial_t w^{\varepsilon} + \partial_x f(w^{\varepsilon}) = \varepsilon t \beta \partial_{xx} w^{\varepsilon} + \varepsilon^2 t^2 \gamma \partial_{xxx} w^{\varepsilon}, \qquad x \in \mathbb{R}, \ t > 0,$$

where  $f: \mathbb{R} \to \mathbb{R}$  is a given smooth function.

Change of variables

$$w^{\varepsilon}(x,t) = w(\xi)$$
 with  $\xi = \frac{x}{t}$ .

• w solution of

$$-\xi w' + f(w)' = \varepsilon \beta w'' + \varepsilon^2 \gamma w''', \tag{4}$$

with boundary conditions given by

$$w(-\ell) = w_L \quad \text{and} \quad w(\ell) = w_R,$$
 (5)

with  $\ell > 0$  large enough.

### Numerical scheme - Mesh

- Interval  $[-\ell, \ell]$  discretized with N+1 cells of length  $\Delta \xi = \frac{2\ell}{N+1}$ :  $|\xi_i, \xi_{i+1}\rangle$ ,  $\xi_i = -\ell + i\Delta \xi$ .
- Notation  $w_i \approx w(\xi_i)$ .
- Need of ghost cells for the boundary conditions:  $i = -2, \dots, N+3$ .

### Numerical scheme - 4th order Finite Differences

For a given vector  $(X_i)_{i=-2,...,N+3}$  and a smooth function g(X), we consider the following discrete operators, for i=1,...,N:

$$\overline{g(X)}_{i}' = \frac{g(X_{i-2}) - 8g(X_{i-1}) + 8g(X_{i+1}) - g(X_{i+2})}{12\Delta\xi},$$

$$\overline{X}_{i}'' = \frac{-X_{i-2} + 16X_{i-1} - 30X_{i} + 16X_{i+1} - X_{i+2}}{12\Delta\xi^{2}},$$

$$\overline{X}_{i}''' = \frac{X_{i-3} - 8X_{i-2} + 13X_{i-1} - 13X_{i+1} + 8X_{i+2} - X_{i+3}}{8\Delta\xi^{3}}.$$

As soon as  $U_i = U(\xi_i)$ , where  $U(\xi)$  denotes a smooth function, we get

$$\overline{g(U)}_{i}' = g(U)'(\xi_{i}) + \mathcal{O}(\Delta \xi^{4}),$$

$$\overline{U}_{i}'' = U''(\xi_{i}) + \mathcal{O}(\Delta \xi^{4}),$$

$$\overline{U}_{i}''' = U'''(\xi_{i}) + \mathcal{O}(\Delta \xi^{4}).$$

### Numerical scheme - 4th order scheme

The finite difference scheme applied to our problem (4) and (5) writes:

$$-\xi_i \overline{w}_i' + \overline{f(w)}_i' = \varepsilon \beta \overline{w}_i'' + \varepsilon^2 \gamma \overline{w}_i''', \quad i = 1, \dots, N,$$
 (6)

supplemented by the following boundary conditions [see 8]:

$$w_{-2} = w_{-1} = w_0 = w_L, \quad w_{N+1} = w_{N+2} = w_{N+3} = w_R.$$
 (7)

#### Existence result

We are able to state the following result  $[see \ 9]$ .

#### Theorem

Let  $\varepsilon > 0$  be given and assume the existence of

$$M_{f'} := \sup_{w \in \mathbb{R}} |f'(w)|.$$

Then there exists  $\Delta \xi_0 \leq \sqrt{\varepsilon \beta}$  depending on  $\beta$ ,  $\varepsilon$ ,  $\ell$  and  $M_{f'}$  such that for  $\Delta \xi \leq \Delta \xi_0$ , there exists a solution  $w^{\Delta} = (w_i)_{i=1,...,N}$  to the scheme (6)–(7).

<sup>&</sup>lt;sup>9</sup>Berthon, Bessemoulin-Chatard, AC, Foucher 2019 (Calcolo)

## Idea of the proof

• We rewrite the problem as

$$\mathcal{E}(w^{\Delta}) = 0,$$

where

$$\mathcal{E}(w^{\Delta})_{i} = \varepsilon \beta \overline{w}_{i}^{"} + \varepsilon^{2} \gamma \overline{w}_{i}^{""} + \xi_{i} \overline{w}_{i}^{"} - \overline{f(w)}_{i}^{"}, \quad i = 1, \dots, N,$$

with

$$w_{-2} = w_{-1} = w_0 = w_L, \quad w_{N+1} = w_{N+2} = w_{N+3} = w_R.$$

• A change of variable let us rewrite this problem as

$$\tilde{\mathcal{E}}(\tilde{w}^{\Delta}) = 0,$$

with

$$\tilde{w}_{-2} = \tilde{w}_{-1} = \tilde{w}_0 = \tilde{w}_{N+1} = \tilde{w}_{N+2} = \tilde{w}_{N+3} = 0.$$

## Key lemma: Zeros of a vector field

We will use the following lemma [see 10], which is a consequence of Brouwer's fixed point theorem.

#### Lemma

Let  $F: \mathbb{R}^N \to \mathbb{R}^N$  be a continuous function satisfying

$$F(x) \cdot x \le 0 \quad \text{if } ||x|| = k,$$

for some k > 0. Then there exists a point  $x \in B(0, k)$  such that F(x) = 0.

A technical study of the scalar product  $\tilde{\mathcal{E}}(\tilde{w}^{\Delta}).\tilde{w}^{\Delta}$  and Poincaré inequality give us the proof of our existence theorem.

<sup>&</sup>lt;sup>10</sup>Evans 1998 (Book)

## Continuation-type Newton method

• For  $\varepsilon = \mathcal{O}(1)$ , the nonlinear system

$$\mathcal{E}(w_{\varepsilon}^{\Delta}) = 0,$$

where

$$\mathcal{E}(w_{\varepsilon}^{\Delta})_{i} = \varepsilon \beta \overline{w}_{i}^{"} + \varepsilon^{2} \gamma \overline{w}_{i}^{""} + \xi_{i} \overline{w}_{i}^{"} - \overline{f(w)}_{i}^{"}, \quad i = 1, \dots, N,$$

with

$$w_{-2} = w_{-1} = w_0 = w_L$$
,  $w_{N+1} = w_{N+2} = w_{N+3} = w_R$ ,

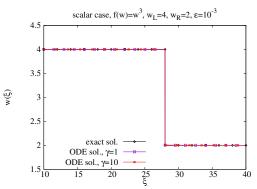
is easily solvable with a (damping [see 11]) Newton method.

- When  $\varepsilon \to 0$ , it is essential to have a good initial guess to make the Newton method converge.
- The idea is to decrease  $\varepsilon$  step by step:  $w_{\varepsilon}^{\Delta}$  is the initial guess of the Newton method when solving  $\mathcal{E}(w_{\varepsilon-\Delta\varepsilon}^{\Delta}) = 0$ .

<sup>&</sup>lt;sup>11</sup>Ralph 1994 (MOR)

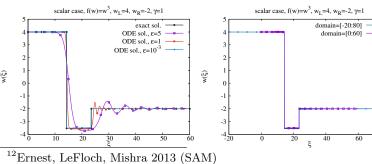
## Numerical tests with $f(w) = w^3$

- Classical case:  $w_L = 4$ ,  $w_R = 2$ .
- Exact solution: shock at  $\xi = 28 = \frac{f(w_L) f(w_R)}{w_L w_R}$ .
- Domain  $\mathcal{D} = [10, 40], N = 1000 \ \beta = 1 \text{ and } \varepsilon = 10^{-3}.$
- Two values of  $\gamma$  (1 and 10) are considered to verify that  $\gamma$  has no influence on the solution.



#### Application to a scalar problem Application to a p-system problem

- Non classical case:  $w_L = 4$ ,  $w_R = -2$ ,  $\beta = 1$  and  $\gamma = 1$ .
- Exact solution [see 12]: intermediate state given by  $w^{\star} = -w_L + \frac{\sqrt{2}}{2} \approx -3.5286$  and two shocks, one at  $\xi = \frac{f(w_L) - f(w^*)}{w_L - w^*} \approx 14.3366$ , the other at  $\xi = \frac{f(w_R) - f(w^*)}{w_R - w^*} \approx 23.5082.$
- Domain  $\mathcal{D} = [0, 60]$  or [-20, 80], N = 2000. Different values of  $\varepsilon$ .



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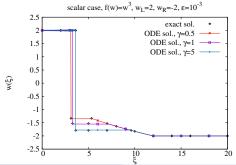
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## From PDE to ODE Application to a scalar problem Application to a p-system problem

- Non classical case:  $w_L = 2$ ,  $w_R = -2$ ,  $\beta = 1$ .
- Exact solution [see 12]: intermediate state given by  $w^* = -w_L + \frac{\sqrt{2}}{3\sqrt{\gamma}}$ . A shock and a rarefaction wave given by

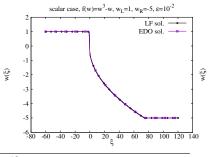
$$\begin{cases} w^{\star}, & \xi \leq f'(w^{\star}), \\ f'^{-1}(\xi), & f'(w^{\star}) \leq \xi \leq f'(w_R), \\ w_R, & f'(w_R) \leq \xi. \end{cases}$$

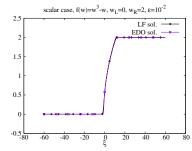
• Domain  $\mathcal{D} = [0, 60], N = 2000, \varepsilon = 10^{-3}.$ 



## Numerical tests with $f(w) = w^3 - w$

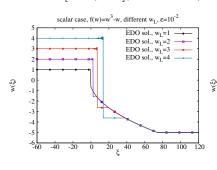
- Classical solutions [see 13]:  $w_L = 1$ ,  $w_R = -5$  (Left) or  $w_L = 0$ ,  $w_R = 2$  (Right),  $\beta = 5$  and  $\gamma = 37.5$ .
- Our approach:  $\mathcal{D} = [-60, 120]$  (Left),  $\mathcal{D} = [-60, 60]$  (Right), N = 2000,  $\varepsilon = 10^{-2}$ .
- FV Lax-Friedrichs scheme:  $N = 5 \times 10^4$ ,  $\Delta t = 2 \times 10^{-5}$ .

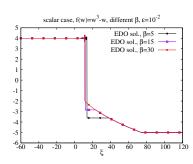




<sup>&</sup>lt;sup>13</sup>Chalons, LeFloch 2001 (Numer. Math.)

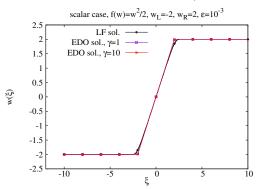
- From classical to non classical solutions [see 13].
- Left:  $w_R = -5$ ,  $w_L$  varying from 1 to 4,  $\beta = 5$ ,  $\gamma = 37.5$ ,  $\mathcal{D} = [-60, 120]$ , N = 2000,  $\varepsilon = 10^{-2}$ .
- Right:  $w_R = -5$ ,  $w_L = 4$ ,  $\beta$  varying from 5 to 30,  $\gamma = 37.5$ ,  $\mathcal{D} = [-60, 120]$ , N = 2000,  $\varepsilon = 10^{-2}$ .



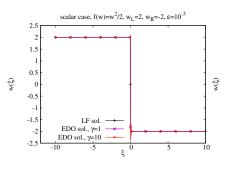


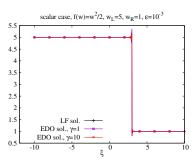
## Numerical tests with $f(w) = \frac{w^2}{2}$ (Burgers)

- This problem only admits classical solutions.
- Case of a rarefaction wave:  $w_L = -2$ ,  $w_R = 2$ ,  $\beta = 1$ ,  $\gamma = 1$  or 10.
- Our approach:  $\mathcal{D} = [-10, 10], N = 2000, \varepsilon = 10^{-3}.$
- FV Lax-Friedrichs scheme:  $N = 10^4$ ,  $\Delta t = 10^{-4}$ .



- Case of a stationary shock (Left):  $w_L = 2$ ,  $w_R = -2$ .
- Case of a non stationary shock (Right):  $w_L = 5$ ,  $w_R = 1$ .
- Other parameters are unchanged.





## From PDE to ODE Application to a scalar problem Application to a p-system problem

- From PDE to ODE
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- $\bigcirc$  Application to a p-system problem

### From p-system to ODE

• Considering the  $2 \times 2$  diffusive-dispersive system, introduced by Joseph and LeFloch [see 14]

$$\begin{cases} \partial_t w^{\varepsilon} - \partial_x v^{\varepsilon} = 0, & x \in \mathbb{R}, \ t > 0, \\ \partial_t v^{\varepsilon} - \partial_x p(w^{\varepsilon}) = \varepsilon t \beta \partial_{xx} v^{\varepsilon} + \varepsilon^2 t^2 \gamma \partial_{xxx} w^{\varepsilon}, \end{cases}$$

where  $p: \mathbb{R} \to \mathbb{R}$  is a given smooth function.

- Focus on Riemann problems and so on self-similar solutions.
- Change of variables

$$w^{\varepsilon}(x,t) = w(\xi)$$
 and  $v^{\varepsilon}(x,t) = v(\xi)$  with  $\xi = \frac{x}{t}$ .

<sup>&</sup>lt;sup>14</sup>Joseph, LeFloch 2007 (P ROY SOC EDINB A)

• We obtain

$$\begin{cases} -\xi w' - v' = 0, \\ -\xi v' - p(w)' = \varepsilon \beta v'' + \varepsilon^2 \gamma w''', \end{cases}$$

supplemented by boundary conditions

$$(v, w)(-\ell) = (v_L, w_L)$$
 and  $(v, w)(\ell) = (v_R, w_R),$ 

with  $\ell > 0$  large enough.

• Using  $v' = -\xi w'$ , w is governed by a nonlinear equation independent of v

$$(\xi^2 + \varepsilon \beta) w' - p(w)' = -\varepsilon \beta \xi w'' + \varepsilon^2 \gamma w''', \tag{8}$$

supplemented by the boundary conditions

$$w(-\ell) = w_L \quad \text{and} \quad w(\ell) = w_R.$$
 (9)

• Problem (8)-(9) contains the full structure of the expected Riemann solution.

- Analysis of (8) [see 15] shows some degeneracy for  $\xi = 0$ .
- Must be studied into the two regions  $[-\ell, 0)$  and  $(0, \ell]$  separately.
- The viscous term governed by  $\varepsilon\beta\xi$  is of prime importance, but the viscosity vanishes as soon as  $\xi = 0$ . From a numerical point of view, we have to avoid  $\xi = 0$ .
- We consider two intervals  $[-\ell, -\xi^*]$  and  $[\xi^*, \ell]$  separately where  $\xi^* > 0$  is a given constant small enough.
- We impose boundary conditions

$$w(-\xi^*) = w^*$$
 and  $w(\xi^*) = w^*$ ,

where  $\xi^*$  has to be fixed and  $w^*$  has to be determined.

<sup>&</sup>lt;sup>15</sup>Joseph, LeFloch 2007 (P ROY SOC EDINB A)

### Numerical scheme - Finite differences

Assume that the state  $w^* \in \mathbb{R}$  is given. We use 4th order Finite Differences on the right interval  $[\xi^*, \ell]$  (resp. on the left interval  $[-\ell, -\xi^*]$ ).

- Interval  $[\xi^*, \ell]$  is discretized with N+1 cells  $[\xi_i, \xi_{i+1})$  of size  $\Delta \xi = (\ell \xi^*)/(N+1)$ :  $\xi_i = \xi^* + i\Delta \xi$ .
- For boundary conditions, we define  $\xi_i$  for  $i = -2, \dots, N+3$ .
- We denote  $w_i$  an approximation of  $w(\xi_i)$  for  $i = 1, \dots, N$  and define the scheme

$$(\xi_i^2 + \varepsilon \beta) \overline{w}_i' - \overline{p(w)}_i' = -\varepsilon \beta \xi_i \overline{w}_i'' + \varepsilon^2 \gamma \overline{w}_i''', \quad i = 1, \dots, N,$$
(10)

completed with the following boundary conditions

$$w_{-2} = w_{-1} = w_0 = w^*, \quad w_{N+1} = w_{N+2} = w_{N+3} = w_R.$$
 (11)

### Determination of $w^*$ - Mass conservation

- Conservation law: total mass of w must be preserved.
- Initial mass of w given by

$$M_0 = \ell(w_L + w_R).$$

• Total mass of the approximated solution  $w^{\Delta}$  depends on  $w^{\star}$  and reads

$$\begin{split} M(w^{\star}) &= \Delta \xi w_L + \sum_{i=1}^N \Delta \xi w_i(w_L, w^{\star}) + 2 \xi^{\star} w^{\star} \\ &+ \sum_{i=1}^N \Delta \xi w_i(w^{\star}, w_R) + \Delta \xi w_R. \end{split}$$

•  $w^*$  must be solution of the following nonlinear equation:

$$M(w^{\star}) = M_0.$$

## Determination of $w^*$ - Dichotomy technique

• We initialize the dichotomy algorithm as follows:

$$(w_{\rm inf}, w_{\rm sup}) = \begin{cases} (w_L, w_R) & \text{if } M(w_L) < M(w_R), \\ (w_R, w_L) & \text{elsewhere,} \end{cases}$$
$$w_0^{\star} = \frac{1}{2}(w_L + w_R).$$

- For iterations  $k \geq 1$ , we compute the left and right solutions  $w^{\Delta}(w_L, w_{k-1}^{\star})$  and  $w^{\Delta}(w_{k-1}^{\star}, w_R)$  and we deduce  $M_k = M(w_{k-1}^{\star})$ .
- If  $M_k < M_0$  then  $w_{\inf} = w_{k-1}^{\star}$ , else  $w_{\sup} = w_{k-1}^{\star}$ , and we compute the new iterate value  $w_k^{\star} = \frac{1}{2}(w_{\inf} + w_{\sup})$ .
- In practice, we accept a small mass error of  $10^{-6}$ .

#### Existence result

We are able to state the following result [see 16].

#### Theorem

Let  $\varepsilon > 0$  be given and  $\xi^* > 2\Delta \xi$ . Assume the existence of

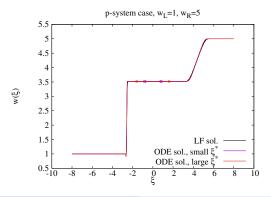
$$M_{p'} := \sup_{w \in \mathbb{R}} |p'(w)|.$$

Then there exists  $\Delta \xi_0 \leq \sqrt{\varepsilon \beta}$  depending on  $\beta$ ,  $\varepsilon$ ,  $\ell$ ,  $\xi^*$  and  $M_{p'}$  such that for  $\Delta \xi \leq \Delta \xi_0$ , there exists a solution  $w^{\Delta} = (w_i)_{i=1,\dots,N}$  to the scheme (10) with the boundary conditions (11).

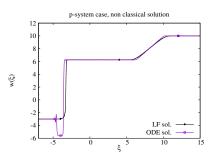
<sup>&</sup>lt;sup>16</sup>Berthon, Bessemoulin-Chatard, AC, Foucher 2019 (Calcolo)

## Numerical tests with $p(w) = \frac{w^3}{3} + w$

- Classical case:  $w_L = 1$ ,  $w_R = 5$ ,  $\beta = 1$ ,  $\gamma = 1$ .
- Our approach:  $\ell = 8, \, \xi^*$ : 0.8 or 1.6, N = 1000,  $\varepsilon = 4 \times 10^{-2}$ .
- FV Lax-Friedrichs scheme:  $N = 10^4$ ,  $\Delta t = 10^{-4}$ .



- Non classical case:  $w_L = -3$ ,  $w_R = 10$ ,  $\beta = 1$ ,  $\gamma = 20$ .
- Our approach:  $\ell = 20, N = 1000, \varepsilon = 2.5 \times 10^{-2}$ .
- FV Lax-Friedrichs scheme:  $N = 10^4$ ,  $\Delta t = 10^{-4}$ .



#### Conclusions

- A new numerical approach to approximate (non classical) Riemann solutions of system of conservation laws.
- Solutions seen as limit solutions of diffusive-dispersive problem.
- Use self-similarity and Dafermos technique to obtain an ODE problem.
- Gives quite good numerical results on classical and non classical tests.
- Future works: more complex system problems as Shallow-Water equations.

From PDE to ODE Application to a scalar problem Application to a p-system problem

Thank you for your attention!