

Bayesian methods for inverse problems

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Inverse problems

Encountered when **indirect measurements**, y , of **quantity of interest**, u , is available

$$y \approx \mathcal{G}(u)$$

with \mathcal{G} well-posed.

- \mathcal{G}^{-1} might not be well-posed
- measurements are typically inaccurate, hence y might lie outside of range of \mathcal{G}

Example. Inverse heat equation

$$v_t - v_{xx} = 0, \quad x \in (0, 1), \quad t > 0$$

$$v(0, t) = v(1, t) = 0, \quad t \geq 0.$$

Find $u(x) := v(x, 0)$, given measurements $y(x) \approx v(x, T)$.

We have

$$v(x, t) = \sum_{n=1}^{\infty} c_n e^{-(n\pi)^2 t} \sin n\pi x$$

with c_n satisfying $u(x) = \sum_{n=1}^{\infty} c_n \sin n\pi x$.

Instability in data: For

$$y(x) - v(x, T) = \alpha \sin 5\pi x,$$

$$\tilde{u}(x) - u(x) = \alpha e^{25\pi^2 T} \sin 5\pi x$$

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Example. Inverse problem for an elliptic PDE:

$$\begin{aligned} -\nabla \cdot (u(x) \nabla p(x)) &= f, & x \in \Omega \subset \mathbb{R}^d \\ p(x) &= 0, & x \in \partial\Omega. \end{aligned}$$

Find u , given $y_j = p(x_j) + \eta_j$, $j = 1, \dots, J$, $\eta_j \sim \mathcal{N}(0, \gamma_j)$, i.i.d.

$y = \mathcal{G}(u) + \eta$ with

- forward map $\mathcal{G} : u \mapsto \begin{pmatrix} p(x_1) \\ \vdots \\ p(x_J) \end{pmatrix}$

data $y = \begin{pmatrix} y_1 \\ \vdots \\ y_J \end{pmatrix}$ and the noise vector $\eta = \begin{pmatrix} \eta_1 \\ \vdots \\ \eta_J \end{pmatrix}$

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Classical approach

aiming to find *a reasonable estimate* of the quantity of interest

- Least-squares solution

$$u^* = \arg \min_{u \in X} \|y - \mathcal{G}(u)\|_Y$$

- Regularised solution

$$u^* = \arg \min_{u \in X} \|y - \mathcal{G}(u)\|_Y^2 + \alpha \mathcal{J}(u)$$

(typically $\mathcal{J}(u) = \|u\|_E^p$ for $E \subseteq X$ and $p \geq 1$)

Bayesian approach

For estimating u from

$$y = \mathcal{G}(u) + \eta$$

- u , y , and η , are modelled as random variables:
 - Degree of information about values of these variables are expressed in the form of probability distributions
- The solution is the posterior probability distribution given via the Bayes rule

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Bayesian approach

Let

$$y = \mathcal{G}(u) + \eta$$

with $y \in \mathbb{R}^J$, $u \in X$, (X separable Banach spaces), and suppose

- prior $u \sim \mu_0$
- statistics of noise is known: $\eta \sim \rho_\eta$
- u and η are independent, $u \perp \eta$

Bayes' rule: $\text{Prob}(u \mid \text{data}) \propto \text{Prob}(\text{data} \mid u) \text{Prob}(u)$

Noting that $\text{data} \mid u \sim \rho_\eta(\cdot - \mathcal{G}(u))$ we have

$$\mu^y(\mathrm{d}u) \propto \rho_\eta(y - \mathcal{G}(u)) \mu_0(\mathrm{d}u).$$

(when well-defined)

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Example. Let $X = Y = \mathbb{R}$

$$y = g(u) + \eta, \quad \eta \sim \mathcal{N}(0, \gamma^2)$$

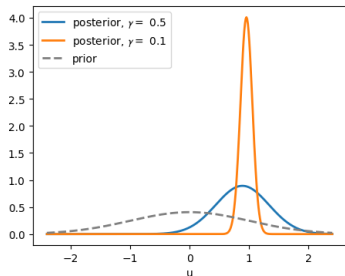
$$\mu_0 \sim \mathcal{N}(0, 1)$$

Then

$$\mu^y(du) \propto e^{-\frac{1}{2\gamma^2}|y-g(u)|^2} e^{-\frac{1}{2}u^2} du$$

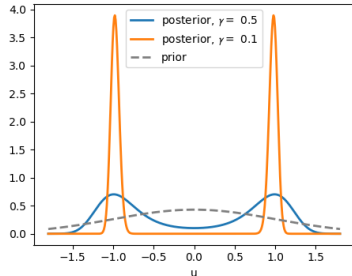
- $g(u) = u,$

$$\mu^y \sim \mathcal{N}\left(\frac{y}{1+\gamma^2}, \frac{\gamma^2}{1+\gamma^2}\right)$$



- $g(u) = u^2,$

$$\rho_{\mu^y} = e^{-\frac{1}{2\gamma^2}|y-u^2|^2} e^{-\frac{1}{2}u^2}$$



Outline

- 1 Well-posedness
 - Well-definedness and stability in data
 - Prior modelling
- 2 Approximation of the posterior
- 3 Consistency
- 4 MCMC methods

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Well-definedness of posterior

$$\frac{d\mu^y}{d\mu_0}(u) \propto \rho_\eta(y - \mathcal{G}(u)) =: e^{-\Phi(u,y)}, \quad Z := \int_X e^{-\Phi(u,y)} \mu_0(du)$$

ρ_η density of measure \mathbb{Q} on $Y = \mathbb{R}^J$,
 X separable Banach space

Assume that

- $\mu_0(X) = 1$
- $\Phi : X \times \mathbb{R}^J \rightarrow \mathbb{R}$ is $\mu_0 \otimes \mathbb{Q}$ measurable
- $0 < Z < \infty$.

Then $\mu^y \ll \mu_0$ and

$$\frac{d\mu^y}{d\mu_0}(u) = \frac{1}{Z} \exp(-\Phi(u,y))$$

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Stability in data

If $y, y' \in \mathbb{R}^J$ are close, μ^y and $\mu^{y'}$ remain 'close':

To measure the distance between probability measures we use

$$\text{Hellinger metric: } d_{\text{Hell}}^2(\mu, \mu') = \frac{1}{2} \int_X \left(\sqrt{\frac{d\mu}{d\nu}} - \sqrt{\frac{d\mu'}{d\nu}} \right)^2 d\nu$$

Suppose also that for $\max(|y_1|, |y_2|) < r$

$$|\Phi(u, y_1) - \Phi(u, y_2)| \leq M(r, \|u\|_X) |y_1 - y_2|$$

$$\text{with } \int_X M(r, \|u\|_X) d\mu_0 < \infty$$

Then

$$d_{\text{Hell}}(\mu^{y_1}, \mu^{y_2}) \leq C |y_1 - y_2|$$

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- With Hellinger metric (for $f : X \rightarrow E$ in $L^2_\mu \cap L^2_{\mu'}$)

$$\|\mathbb{E}^\mu f(u) - \mathbb{E}^{\mu'} f(u)\|_E \leq C d_{\text{Hell}}(\mu, \mu')$$

We have

$$\begin{aligned} \mathbb{E}^\mu f - \mathbb{E}^{\mu'} f &= \int_X f d\mu - \int_X f d\mu' = \int f \left(\frac{d\mu}{d\nu} - \frac{d\mu'}{d\nu} \right) d\nu \\ &= \int f(u) \left(\sqrt{\frac{d\mu}{d\nu}} + \sqrt{\frac{d\mu'}{d\nu}} \right) \left(\sqrt{\frac{d\mu}{d\nu}} - \sqrt{\frac{d\mu'}{d\nu}} \right) d\nu \end{aligned}$$

Hence

$$\begin{aligned} \|\mathbb{E}^\mu f - \mathbb{E}^{\mu'} f\|_E &\leq \int \|f\|_E \sqrt{\frac{d\mu}{d\nu}} \left| \sqrt{\frac{d\mu}{d\nu}} - \sqrt{\frac{d\mu'}{d\nu}} \right| d\nu \\ &\quad + \int \|f\|_E \sqrt{\frac{d\mu'}{d\nu}} \left| \sqrt{\frac{d\mu}{d\nu}} - \sqrt{\frac{d\mu'}{d\nu}} \right| d\nu \\ &\leq 2(\mathbb{E}^\mu \|f\|_E^2 + \mathbb{E}^{\mu'} \|f\|_E^2)^{\frac{1}{2}} d_{\text{Hell}}(\mu, \mu') \end{aligned}$$

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Well-definedness. Assume that

- $\mu_0(X) = 1$
- $\Phi : X \times \mathbb{R}^J \rightarrow \mathbb{R}$ is $\mu_0 \otimes \mathbb{Q}$ measurable
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Then $\mu^y \ll \mu_0$ and

$$\frac{d\mu^y}{d\mu_0}(u) = \frac{1}{Z} \exp(-\Phi(u, y))$$

(Stuart '10, D. Stuart '17)

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(Stuart '10)

If ρ_η is Gaussian, blue conditions are enough for continuity in d_{Hell} (Latz '20)

The prior

- $(X, \|\cdot\|)$ separable Banach space with basis $\{\psi_j\}_{j \in \mathbb{N}}$
- Define μ_0 through Karhunen-Loève expansion of its draws:

$$u(x) = m_0 + \sum_{j \in \mathbb{N}} \alpha_j \xi_j \psi_j(x)$$

$m_0 \in X$ given

ξ_j i.i.d random variables,

$\{\alpha_j\}$ decreasing sequence determining smoothness of u

Example: $X = L^2(0, 1)$, $\psi_j(x) = \sqrt{2} \sin(2j\pi x)$, $m_0 = 0$

$\alpha_j = j^{-s}$, with $s > 1/2$, $\mathbb{E}(\xi_1^2) < \infty$

$$\mathbb{E}\|u\|_{L^2}^2 = \mathbb{E}(\xi_1^2) \sum_j \alpha_j^2 < \infty \quad \text{hence} \quad \mu(L^2) = 1$$

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- Gaussian μ_0 :

$$X \subseteq L^2(D), D \subset \mathbb{R}^d,$$

$\{\psi_j\}$ an orthonormal basis (regular enough),

$$\xi_j \sim c \exp(-\frac{1}{2}|x|^2), \quad \alpha_j = j^{-\frac{s}{d}}$$

$$\mu_0(C^t) = 1, \text{ for } t < s - \frac{d}{2}$$

- Besov μ_0 :

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To show wellposedness we need to:

- Find X so that $\mathcal{G} : X \rightarrow \mathbb{R}^J$ is continuous
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- Choose μ_0 such that $\mu_0(X) = 1$:

- $\mathcal{G} \in C^{0,1}(X)$:

Let $0 < m := \inf_{x \in D} \{u_1(x), u_2(x)\}$ and $L = L(\|u_1\|_{L^\infty}, \|u_2\|_{L^\infty})$

$$|\mathcal{G}(u_1) - \mathcal{G}(u_2)| \leq \frac{L}{m} \|u_1 - u_2\|_{L^\infty},$$

hence $X \subset \{w \in L^\infty : \inf_x w(x) > 0\}$

- Choose μ_0 such that $\mu_0(X) = 1$:

* Let $\xi_j \sim \mathcal{C} \exp(-\frac{1}{2}|x|^2)$, $\alpha_j = j^{-\frac{s}{d}}$ with $s > \frac{d}{2}$

define $\tilde{\mu}_0$ through

$$\tilde{u}(x) = \sum_{j \in \mathbb{N}} \alpha_j \xi_j \psi_j(x)$$

then $\tilde{\mu}_0(C^t(D)) = 1$ for $t < s - \frac{d}{2}$,

* Set $u(x) = g(\tilde{u}(x)) := e^{\tilde{u}(x)}$,

then $u \sim \mu_0$ with $\mu_0(X) = 1$ where $X = \{w \in C^t : \inf_x w(x) > 0\}$

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- Choose μ_0 such that $\mu_0(X) = 1$:

* Let $\xi_j \sim c \exp(-\frac{1}{2}|x|^2)$, $\alpha_j = j^{-\frac{s}{d}}$ with $s > \frac{d}{2}$

define $\tilde{\mu}_0$ through

$$\tilde{u}(x) = \sum_{j \in \mathbb{N}} \alpha_j \xi_j \psi_j(x)$$

then $\tilde{\mu}_0(C^t(D)) = 1$ for $t < s - \frac{d}{2}$,

* Set $u(x) = g(\tilde{u}(x)) := e^{\tilde{u}(x)}$,

then $u \sim \mu_0$ with $\mu_0(X) = 1$ where $X = \{w \in C^t : \inf_x w(x) > 0\}$

- Then μ with

$$\frac{d\mu}{d\mu_0} \propto \exp(-\Phi(u, y)) \text{ is wellposed.}$$

Inverse elliptic problem

$$\frac{d\mu}{d\mu_0} \propto \exp\left(-\frac{1}{2}|y - \mathcal{G}(u)|_{\Gamma}^2\right)$$

Summary statistics

- point estimators: conditional mean $\int_X u d\mu$
most likely functions under μ in X
- $\int_X F(u) d\mu$

Need to approximate \mathcal{G} and μ

Outline

- 1 Well-posedness
 - Well-definedness and stability in data
 - Prior modelling
- 2 Approximation of the posterior
- 3 Consistency
- 4 MCMC methods

Consider μ and μ^N :

$$\frac{d\mu}{d\mu_0}(u) \propto \exp(-\Phi(u)), \quad \frac{d\mu^N}{d\mu_0}(u) \propto \exp(-\Phi^N(u))$$

Theorem. (Stuart 2010)

Assume that

$$|\Phi(u) - \Phi^N(u)| \leq M(\|u\|_X) \psi(N)$$

where $\int_X M(r, \|u\|_X) d\mu_0 < \infty$ and $\psi(N) \rightarrow 0$ as $N \rightarrow \infty$

Then

$$d_{\text{Hell}}(\mu, \mu^N) \leq C\psi(N).$$

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Then

$$d_{\text{Hell}}(\mu, \mu^N) \leq C \psi(N).$$

$$\begin{aligned}
(d_{\text{Hell}}(\mu, \mu^N))^2 &= \frac{1}{2} \int_X \left(\sqrt{\frac{d\mu}{d\mu_0}} - \sqrt{\frac{d\mu^N}{d\mu_0}} \right)^2 d\mu_0 \\
&= \frac{1}{2} \int_X \left(\frac{1}{\sqrt{Z}} e^{-\frac{1}{2}\Phi} - \frac{1}{\sqrt{Z^N}} e^{-\frac{1}{2}\Phi^N} \right)^2 d\mu_0 \\
&\leq \frac{1}{Z} \int_X (e^{-\frac{1}{2}\Phi} - e^{-\frac{1}{2}\Phi^N})^2 d\mu_0 \\
&\quad + |Z^{-\frac{1}{2}} - (Z^N)^{-\frac{1}{2}}|^2 \int_X e^{-\Phi^N} d\mu_0(u)
\end{aligned}$$

$$\begin{aligned}
|Z^{-\frac{1}{2}} - (Z^N)^{-\frac{1}{2}}|^2 &= \frac{|Z - Z^N|^2}{Z Z^N (Z^{-\frac{1}{2}} + (Z^N)^{-\frac{1}{2}})^2} \\
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Finite dimensional approximation

- $(X, \|\cdot\|)$ Hilbert space with orthonormal basis $\{\psi_j\}_{j \in \mathbb{N}}$
- $P^N : X \rightarrow \mathbb{R}^n$ orthogonal projection onto $W = \text{span}\{\{\psi_j\}_{j=1}^N\}$
- $\Phi^N(u) = \Phi(P^N u)$
- Constructing μ_0 from KL expansion using $\{\psi_j\}$ we get

$$\mu_0 = \mu_0^N \otimes \mu_0^\perp$$

- Then $\mu^N = \nu^N \otimes \mu_0^\perp$ with

$$\frac{d\nu^N}{d\mu_0^N}(u) \propto \exp(-\Phi^N(u)), \quad u \in W$$

$$\|\mathbb{E}^\mu F(u) - \mathbb{E}^{\nu^N} F(u^N, 0)\|_S \leq C\psi(N), \quad (F : X \rightarrow S)$$

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F can be soln operator of the PDE (or some function of it), e.g. $u \mapsto p$ in

Inverse elliptic PDE:

$$\begin{aligned} -\nabla \cdot (u(x) \nabla p(x)) &= f, & x \in \Omega \subset \mathbb{R}^d \\ p(x) &= 0, & x \in \partial\Omega. \end{aligned}$$

Find u , given $y_j = p(x_j) + \eta_j$, $j = 1, \dots, J$, $\eta_j \sim \mathcal{N}(0, \gamma_j)$

$\bar{p} = \mathbb{E}^\mu p$ or $\mathbb{E}^\mu(p - \bar{p}) \otimes (p - \bar{p})$ give an indication of how uncertainty in u is affecting p

Posterior measure: updated prior (using data)

- improved estimation of our degree of info./uncertainty in input results in improved quantification of uncertainty

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Posterior consistency

We look for an estimate of the underlying true u^\dagger from:

$$y_j = \mathcal{G}(u^\dagger) + \eta_j, \quad j = 1, \dots, n$$

with $y_j \in \mathbb{R}^K$,

$$\mathcal{G} : X \rightarrow \mathbb{R}^K, \quad \text{and} \quad \eta_j \sim \mathcal{N}(0, \Gamma), \quad \text{i.i.d.}$$

Given $\mu_0 \sim \mathcal{N}(0, C_0)$ we have

$$\frac{d\mu^{y_1, \dots, y_n}}{d\mu_0}(u) \propto \exp \left(-\frac{1}{2} \sum_{j=1}^n |y_j - \mathcal{G}(u)|_\Gamma^2 \right).$$

Does μ^y concentrate on arbitrarily small neighbourhoods of u^\dagger as $n \rightarrow \infty$ and how fast?

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(*weak consistency*)

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MAP estimators

$$\frac{d\mu}{d\mu_0}(u) \propto \exp(-\Phi(u)), \quad \mu_0 \sim \mathcal{N}(\mathbf{0}, C_0)$$

- If $X = \mathbb{R}^d$, MAP estimators are maximisers of the density function

$$\rho_\mu = c \exp\left(-\Phi(u) - \frac{1}{2}|C_0^{-1/2}u|^2\right)$$

which is maximised at **minimisers** of

$$I(u) := \Phi(u) + \frac{1}{2}|C_0^{-1/2}u|^2$$

- When X is a function space

There is no density, modes can be define topologically

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MAP estimates – topological definition

$(X, \|\cdot\|)$ a separable Banach space; $\mu(X) = 1$

$B_\epsilon(u)$ ball of radius ϵ and centre u in X .

Definition (D., Law, Stuart, Voss 2013)

Any point $\tilde{u} \in X$ satisfying

$$\lim_{\epsilon \rightarrow 0} \frac{\sup_{u \in X} \mu(B_\epsilon(u))}{\mu(B_\epsilon(\tilde{u}))} = 1,$$

is a MAP estimator.

or equivalently \tilde{u} satisfies

$$\lim_{\epsilon \rightarrow 0} \frac{\mu(B_\epsilon(\tilde{u} - h))}{\mu(B_\epsilon(\tilde{u}))} \leq 1, \quad \text{for any } h \in X$$

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$$\lim_{\epsilon \rightarrow 0} \frac{\mu(B_\epsilon(v))}{\mu(B_\epsilon(u))} \stackrel{?}{=} e^{-f(u,v)} \quad (*)$$

► If $X = \mathbb{R}^n$

$$f(u, v) = -I(u) + I(v) \text{ with } I(u) = -\log \rho_\mu(u), \quad \forall u \in \mathbb{R}^n$$

► For X function space

- $\exists Z \subset X$ s.t. $f(u, v) = I(u) - I(v)$ for $u, v \in Z$
- But $\mu(Z) = 0$

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Let μ satisfy

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$\mu_0 \sim \mathcal{N}(0, C_0)$ and $\Phi : X \rightarrow \mathbb{R}$ bounded below and locally Lipschitz.

Then **MAP estimators** are characterised by the **minimisers** of

$$I(u) = \begin{cases} \Phi(u) + \frac{1}{2}\|u\|_E^2 & \text{if } u \in Z, \\ +\infty & \text{otherwise,} \end{cases}$$

where E is the space of admissible shifts of μ_0 .

For $\Phi : X \rightarrow \mathbb{R}$ locally Lipschitz \exists a minimizer $\bar{u} \in Z$ of I .

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$$y_j = \mathcal{G}(u^\dagger) + \eta_j, \quad j = 1, \dots, n$$

$$\frac{d\mu^{y_1, \dots, y_n}}{d\mu_0}(u) \propto \exp\left(-\frac{1}{2} \sum_{j=1}^n |y_j - \mathcal{G}(u)|_\Gamma^2\right); \quad \mu_0 \sim \mathcal{N}(\mathbf{0}, \mathcal{C}_0)$$

MAP estimators: $u_n := \operatorname{argmin}_{u \in \mathcal{Z}} \left\{ \sum_{j=1}^n |y_j - \mathcal{G}(u)|_\Gamma^2 + \frac{1}{2} \|u\|_{\mathcal{Z}}^2 \right\}.$

$$u_n := \operatorname{argmin}_{u \in Z} \left\{ \Phi(u, y) + \frac{1}{2} \|u\|_Z^2 \right\}.$$

Theorem.

Assume that

$G: X \rightarrow \mathbb{R}_+$ is locally Lipschitz and
 $u^\dagger \in Z$.

Then

- $G(u_n) \rightarrow G(u^\dagger)$ in probability.
- If \mathcal{G} is injective $\|u_n - u^\dagger\|_X \rightarrow 0$ in probability.

Otherwise, $\exists u^* \in Z$ and a subseq of $\{u_n\}_{n \in \mathbb{N}}$ such that
 $\|u_n - u^\dagger\|_X \rightarrow 0$ in probability. For any such u^* , $G(u^*) = G(u^\dagger)$.

If $u^\dagger \in X$, $G(u_n) \rightarrow G(u^\dagger)$ in probability.

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Markov Chain Monte Carlo methods

Approximate μ given by $\frac{d\mu}{d\mu_0}(u) \propto e^{-\phi(u)}$, using a *sum of Dirac measures*:

$$\mathbb{E}_\mu f = \int_X f(u) \mu(du) \approx \frac{1}{N} \sum_{n=1}^N f(u^{(n)})$$

where $\{u^{(n)}\}_{n=1}^N$ is a Markov chain.

Recall: The sequence $\{u^{(n)}\}_{n=1}^\infty$ is called a Markov chain if

$$\Pr[u^{(j)} = v_j | u^{(1)} = v_1, \dots, u^{(j-1)} = v_{j-1}] = \Pr[u^{(j)} = v_j | u^{(j-1)} = v_{j-1}]$$

Markov/transition Kernel $P : X \times \mathcal{B}(X) \rightarrow [0, 1]$

$$\int_B P(v, du) = P(v, B) := \Pr[u^{(j)} \in B | u^{(j-1)} = v]$$

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Markov Chain Monte Carlo methods

- construct a **Markov kernel**, P , that
 - can be sampled from
 - has μ as its **invariant distribution**
- draw iterative samples $\{u^{(n)}\}_{n=1}^N$ from P to approximate $\mathbb{E}_\mu f$ as

$$\int_X f(u) \mu(du) \approx \frac{1}{N} \sum_{n=1}^N f(u^{(n)})$$

- The Markov chain with kernel P is **invariant** wrt μ if

$$\int_X \mu(du)P(u, \cdot) = \mu(\cdot)$$

- The Markov kernel is said to satisfy **detailed balance** wrt μ if

$$\mu(du)P(u, dv) = \mu(dv)P(v, du)$$

The resulting Markov chain is then said to be *reversible* wrt μ .

reversible wrt $\mu \implies$ invariant wrt μ

Metropolis-Hastings Markov chain Monte Carlo

M-H MCMC algorithm

- 1 Set $k = 0$ and pick $u^{(0)} \in X$.
- 2 Propose $v^{(k)} \sim Q(u^{(k)}, dv)$
- 3 Calculate acceptance probability $a_k = a(u^{(k)}, v^{(k)})$
- 4 Set $u^{(k+1)} = \begin{cases} v^{(k)} & \text{with prob } a_k \\ u^{(k)} & \text{otherwise} \end{cases}$
- 5 $k \rightarrow k + 1$ and return to 2.

transition kernel for $\{u^{(k)}\}_{k \in \mathbb{N}}$:

$$P(u, A) = \int_A Q(u, dv) a(u, v) + \int_X \delta_u(A) (1 - a(u, w)) Q(u, dw)$$

$$\implies P(u, dv) = Q(u, dv) a(u, v) + \delta_u(dv) \int_X (1 - a(u, w)) Q(u, dw)$$

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Cotter, D. Stuart '12; D. Stuart '17

- $Q(u, dv) = \mu_0(dv)$ gives *Independent sampler*

- when μ_0 is $\mathcal{N}(0, C)$,

setting $Q(u, \cdot) = \mathcal{N}((1 - \beta^2)u, \beta^2 C)$ gives

preconditioned Crank-Nicolson (pCN) method

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$Q(u, \cdot) = \mathcal{N}((1 - \beta^2)u, \beta^2 C)$ is reversible wrt $\mathcal{N}(0, C)$:

$\nu(du, dv) := \mu(du)P(u, dv)$ measure on $X \times X$;

$$\begin{aligned}\hat{\nu}(\xi, \eta) &= \int_{X \times X} e^{i\langle u, \xi \rangle + i\langle v, \eta \rangle} \mu(du)P(u, dv) \\ &= \exp\left(-\frac{1}{2}\|C^{\frac{1}{2}}\eta\|^2 - \frac{1}{2}\|C^{\frac{1}{2}}\xi\|^2 - (1 - \beta^2)^{\frac{1}{2}}\langle C^{\frac{1}{2}}\xi, C^{\frac{1}{2}}\eta \rangle\right) \\ &= \hat{\nu}(\eta, \xi)\end{aligned}$$

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pCN algorithm

- 1 Set $k = 0$ and pick $u^{(0)} \in X$.
- 2 Propose $v^{(k)} = \sqrt{1 - \beta^2} u^{(k)} + \beta \xi^{(k)}$, $\xi^{(k)} \sim \mu_0 = \mathcal{N}(0, \mathcal{C})$
- 3 Calculate acceptance probability $a_k = \min\{1, e^{\Phi(u^{(k)}) - \Phi(v^{(k)})}\}$
- 4 Set $u^{(k+1)} = \begin{cases} v^{(k)} & \text{with prob } a_k \\ u^{(k)} & \text{otherwise} \end{cases}$
- 5 $k \rightarrow k + 1$ and return to 2.

β parameter controlling the degree of locality of proposals

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Convergence to μ

- If the density of $Q(u, \cdot)$ is positive for all u , then

$$d_{\text{Hell}}(P^k(u^{(1)}, \cdot), \nu^N) \rightarrow 0, \quad \text{as } k \rightarrow \infty$$

- ν^N finite-d approximation of μ ; for $f : X \rightarrow E$

$$\|\mathbb{E}^\mu F - \mathbb{E}^{\nu^y} F\|_E \rightarrow 0 \quad \text{as } N, k \rightarrow \infty$$

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Summary

- Wellposedness of Bayesian inverse problems for functions
 - well-definedness of posterior and its stability in data
 - construction of appropriate prior
- Effect of approximation of forward map on the posterior
 - finite-d approximation of the posterior
- Weak consistency of the posterior at the level of the MAP estimators
- Metropolis-Hastings Markov chain Monte Carlo methods (pCN algorithm)

The problem for the practical session

Given

$$y_j = p(x_j) + \xi_j \quad x_j \in (0, 1), \quad j \in \{1, \dots, J\}$$
$$\xi_j \sim \mathcal{N}(0, \gamma^2) \text{ i.i.d.}$$

with p satisfying

$$\frac{d}{dx} \left(u \frac{dp}{dx} \right) = 1, \quad x \in (0, 1)$$
$$p(0) = 0, \quad p(1) = 1,$$

estimate $u \in X = \{w \in C^1(0, 1) : \inf_{(0,1)} w > 0\}$.

- Let $G_j : u \mapsto p(x_j)$. Then μ satisfying

$$\frac{d\mu}{d\mu_0}(u) \propto \exp\left(-\frac{1}{2\gamma^2} \sum_{j=1}^J |y - G_j(u)|^2\right)$$

is well-defined for $\mu_0(X) = 1$.

- **Prior:** μ_0 defined through

$$u = g\left(\sum_{j \in \mathbb{N}} \alpha_j \xi_j \psi_j(x)\right)$$

for $u \sim \mu_0$ and with

- $\{\psi_j(x)\}_{j \in \mathbb{N}} = \{1, \sqrt{2} \cos(2k\pi x), \sqrt{2} \sin(2k\pi x)\}_{k \in \mathbb{N}}$
- $c_1 j^{-s} \leq \alpha_j \leq c_2 j^{-s}$, $s > 3/2$, (to ensure $u \in C^1(0, 1)$)
- $\xi_j \sim \mathcal{N}(0, 1)$ i.i.d.
- $g(\cdot) = c \exp(\cdot)$, (to impose positive lower bound on $u(x)$)

Forward solution of the PDE: Integrating with respect to x gives

$$u(x) \frac{dp(x)}{dx} = x + C$$

with $C \in \mathbb{R}$ constant. Integrating once more and noting that $p(0) = 0$ gives

$$p(x) = \int_0^x \frac{y + C}{u(y)} dy$$

where by $p(1) = 1$ we have

$$C = \frac{1}{\int_0^1 \frac{1}{u(y)} dy} \left(1 - \int_0^1 \frac{y}{u(y)} dy \right)$$

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