

# Positive and entropic schemes by relaxation techniques

Xavier Lhébrard<sup>1</sup>

<sup>1</sup>*LAMA, Université de Marne-la-Vallée*

CEMRACS 2019  
Marseille, August 1st, 2019.

# Introduction

System of conservation laws

$$\partial_t U + \partial_x F(U) = 0.$$

Goal :

- Design robust and accurate scheme

Difficulties :

- Preserves positivity of densities, temperatures, ...
- Compute admissible shocks
- Compromise between accuracy and stability

# Godunov scheme

Godunov scheme = Finite volume scheme

$$U_i^{n+1} - U_i^n + \frac{\Delta t}{\Delta x} (F(U_i, U_{i+1}) - F(U_{i-1}, U_i)) = 0.$$

Numerical flux  $F(U_i, U_{i+1})$

given via the [solution of the Riemann pb](#) with initial data  $U_i, U_{i+1}$ .

$F(U, U) = F(U)$  constant to first order and conservative.

Entropy inequality

$$\partial_t \eta(U) + \partial_x G(U) \leq 0.$$

Discrete entropy inequality

$$\eta(U_i^{n+1}) - \eta(U_i^n) + \frac{\Delta t}{\Delta x} (G(U_i, U_{i+1}) - G(U_{i-1}, U_i)) \leq 0.$$

Interests :

- Convergence proof for scalar and  $2 \times 2$  systems
- A priori bounds
- Computed shocks are physically relevant

# Godunov scheme

Drawbacks of the exact solution :

- complicated to solve
- contains details which will be averaged

Self similar function  $R(\xi, U_l, U_r)$  is an **Approximate Riemann solver**.

$$F(U_l) - \int_{-\infty}^0 (R(\xi, U_l, U_r) - U_l) d\xi = F(U_r) + \int_0^{\infty} (R(\xi, U_l, U_r) - U_r) d\xi$$

Example : **HLL solver**

$$R_{\text{HLL}}(\xi, U_l, U_r) = \begin{cases} U_l, & \xi < \sigma_1 \\ \frac{\sigma_2 U_r - \sigma_1 U_l - F(U_r) + F(U_l)}{\sigma_2 - \sigma_1}, & \sigma_1 < \xi < \sigma_2 \\ U_r, & \sigma_2 < \xi \end{cases}$$

# Stability conditions

Signal speeds Choice of  $\sigma_1$  and  $\sigma_2$  is crucial for stability.

Subcharacteristic conditions

Remark : if the signal **speeds are too large**, the scheme will be **too diffusive**.

Drawback of HLL scheme

- **2-wave solver**, too diffusive on contact discontinuities.

Goal : Design **3-wave or more** solver with the following properties.

- preserves positivity,
- satisfies entropy inequality,
- is sharp across contact discontinuities.

# Suliciu solver

Compressible Euler system

Pressure term  $p(\rho, \varepsilon)$ .

$$\partial_t \rho + \partial_x(\rho u) = 0,$$

$$\partial_t \rho u + \partial_x(\rho u^2 + p) = 0,$$

$$\partial_t E + \partial_x(u(E + p)) = 0.$$

Equation on  $\rho p$

$$\partial_t \rho p + \partial_x(\rho p u) + \rho^2 p'(\rho) \partial_x u = 0,$$

Complex Riemann problem

$$u - \sqrt{p'(\rho)} \quad ; \quad u + \sqrt{p'(\rho)}$$

Suliciu relaxation system

New variable  $\pi$

$$\partial_t \rho + \partial_x(\rho u) = 0,$$

$$\partial_t \rho u + \partial_x(\rho u^2 + \pi) = 0,$$

$$\partial_t E + \partial_x(u(E + \pi)) = 0.$$

Definition of  $\pi$

$$\partial_t \rho \pi + \partial_x(\rho p u) + c^2 \partial_x u = 0,$$

Easy to solve Riemann problem

$$u - \sqrt{\rho^{-2} a^2}; u; \quad u + \sqrt{\rho^{-2} a^2}$$

# Suliciu solver

Relaxation system

$$RHS = \frac{p - \pi}{\varepsilon}$$

Transport-projection between  $t_n$  and  $t_{n+1}$  :

- Initialize  $\pi_l = p(\rho_l, \varepsilon_l)$ ,  $\pi_r = p(\rho_r, \varepsilon_r)$ .
- Solve homogenous relaxation system  $V = (\rho, \rho u, E, \pi)$ .
- Keep variables  $U = (\rho, \rho u, E)$ .

Properties of the scheme [Bouchut, 2004]

- Solver is exact on **contact discontinuities**,
- **Positive and entropic** under the subcharacteristic condition

$$\rho^2 p'(\rho, \varepsilon) \leq a^2$$



# Argument of stability proof

How to prove characteristic conditions are sufficient stability conditions

- For **smooth solutions**, by **Chapman-Enskog expansion**
- For **discontinuous solutions**, by **Entropy extension**

Relaxation framework

$$\partial_t f + \partial_x \mathcal{A}(f) = \frac{Q(f)}{\varepsilon},$$

with equilibrium  $f = M(U)$ .

Relaxation system admits an entropy extension if there exists  $(\mathcal{H}, \mathcal{G})$  satisfying

- Consistency

$$\mathcal{H}(M(U)) = \eta(U)$$

$$\mathcal{G}(M(U)) = G(U)$$

- Minimization principle **[Chen, Levermore, Liu, 1994]**

$$\mathcal{H}(M(U)) \leq \mathcal{H}(f), \quad \forall U = Lf$$

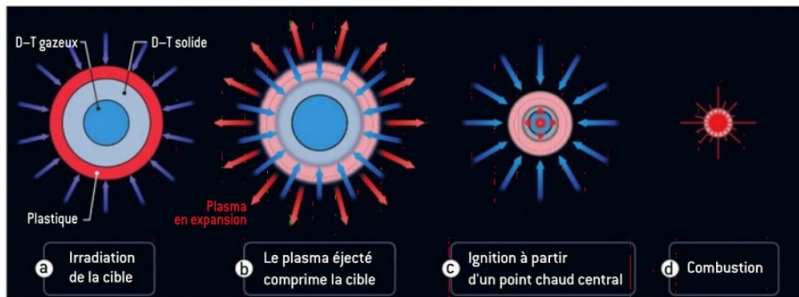
# Bibliography

- 1994, [Chen, Levermore, Liu]
- 1999, 2004, [Bouchut]
- 2011, [Bouchut, Klingenberg, Waagan]
- 2012, 2015, [Berthon, Dubroca, Sangam]
- 2013, [Bouchut, Boyaval]
- 2016 [Bouchut, L]

Application

# Introduction

Application : Inertial confinement fusion.



# Bitemperature Euler system with transverse magnetic field

Nonconservative hyperbolic system

$$\left\{ \begin{array}{l} \partial_t \rho \quad + \partial_x(\rho u_1) = 0, \\ \partial_t(\rho u_1) \quad + \partial_x(\rho u_1^2 + p_e + p_i + B_3^2/2) = 0, \\ \partial_t(\rho u_2) \quad + \partial_x(\rho u_1 u_2) = 0, \\ \partial_t B_3 \quad + \partial_x(u_1 B_3) = 0, \\ \partial_t \overline{\mathcal{E}_e} \quad + \partial_x(u_1(\overline{\mathcal{E}_e} + p_e + c_e B_3^2/2)) - u_1(c_i \partial_x p_e - c_e \partial_x p_i) = S_{ei}, \\ \partial_t \overline{\mathcal{E}_i} \quad + \partial_x(u_1(\overline{\mathcal{E}_i} + p_i + c_i B_3^2/2)) + u_1(c_i \partial_x p_e - c_e \partial_x p_i) = -S_{ei}, \end{array} \right.$$

Two pressure laws and two temperatures :

$$p_\alpha = (\gamma_\alpha - 1)\rho_\alpha \varepsilon_\alpha = n_\alpha k_B T_\alpha, \quad \alpha = e, i.$$

Result : This model has been obtained as the **hydrodynamic limit** of an underlying **conservative kinetic model**.

# Suliciu relaxation for the nonconservative bitemperature MHD system

Bitemperature MHD system

$$\partial_t \rho + u_1 \partial_x \rho + \rho \partial_x u_1 = 0,$$

$$\partial_t u_1 + u_1 \partial_x u_1 + \rho^{-1} \partial_x (\rho_e + \rho_i + B_3^2/2) = 0,$$

$$\partial_t u_2 + u_1 \partial_x u_2 = 0,$$

$$\partial_t B_3 + B_3 \partial_x u_1 + u_1 \partial_x B_3 = 0,$$

$$\partial_t \varepsilon_e + u_1 \partial_x \varepsilon_e + \rho_e^{-1} \rho_e \partial_x u_1 = 0,$$

$$\partial_t \varepsilon_i + u_1 \partial_x \varepsilon_i + \rho_i^{-1} \rho_i \partial_x u_1 = 0.$$

Equations on  $\rho_e$  and  $\rho_i$

$$\partial_t \rho_e + u_1 \partial_x \rho_e + \gamma_e \rho_e \partial_x u_1 = 0,$$

$$\partial_t \rho_i + u_1 \partial_x \rho_i + \gamma_i \rho_i \partial_x u_1 = 0,$$

Complicated to solve Riemann problem

$$u; u \pm \sqrt{\rho^{-2}(\gamma_e \rho \rho_e + \gamma_i \rho \rho_i + \rho B_3^2)}$$

Relaxation system

New variables  $\pi_e$  and  $\pi_i$

$$\partial_t \rho + u_1 \partial_x \rho + \rho \partial_x u_1 = 0,$$

$$\partial_t u_1 + u_1 \partial_x u_1 + \rho^{-1} \partial_x (\pi_e + \pi_i + B_3^2/2) = 0,$$

$$\partial_t u_2 + u_1 \partial_x u_2 = 0,$$

$$\partial_t B_3 + B_3 \partial_x u_1 + u_1 \partial_x B_3 = 0,$$

$$\partial_t \varepsilon_e + u_1 \partial_x \varepsilon_e + \rho_e^{-1} \pi_e \partial_x u_1 = 0,$$

$$\partial_t \varepsilon_i + u_1 \partial_x \varepsilon_i + \rho_i^{-1} \pi_i \partial_x u_1 = 0,$$

Definition of  $\pi_e$  and  $\pi_i$

$$\partial_t \pi_e + u_1 \partial_x \pi_e + \frac{c_e}{\rho} (a^2 - \rho B_3^2) \partial_x u_1 = 0,$$

$$\partial_t \pi_i + u_1 \partial_x \pi_i + \frac{c_i}{\rho} (a^2 - \rho B_3^2) \partial_x u_1 = 0.$$

Easy to solve system

$$u; u \pm \sqrt{\rho^{-2} a^2}$$

# Resolution of Riemann pb

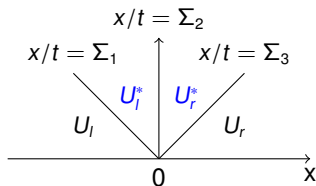
$$V = (\rho, u_l, \varepsilon_e, \varepsilon_i, B_3, \pi_e, \pi_i) \in \mathbb{R}^7$$

Eigenvalues	Mult.	Riemann Invariants
$\lambda_1 = u_l - \frac{a_l}{\rho_l}$	1	$B_3/\rho, w_{1,e}, w_{1,i}, w_{2,e}, w_{2,i}$
$\lambda_2 = u_l^* = u_r^*$	5	$\pi_e + \pi_i + B_3^2/2$
$\lambda_3 = u_r + \frac{a_r}{\rho_r}$	1	$B_3/\rho, w_{1,e}, w_{1,i}, w_{2,e}, w_{2,i}$

with

$$w_{1,\alpha} = \pi_\alpha + c_\alpha B_3^2/2 + \frac{a^2 c_\alpha}{\rho}, \quad w_{2,\alpha} = \varepsilon_\alpha + \frac{B_3^2}{2\rho} - \frac{(\pi_\alpha + c_\alpha B_3^2/2)^2}{2(c_\alpha a)^2}.$$

Explicit resolution of intermediate states.



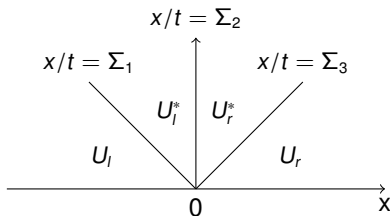
# Nonconservative product

We notice that

$$C_i W_1 - C_e W_2 = C_i \pi_e - C_e \pi_i$$

Thus  $C_i \pi_e - C_e \pi_i$  is a **Riemann invariant** for extremes discontinuities.

Thus the **nonconservative product**  $u \partial_x (C_i \pi_e - C_e \pi_i)$  is **well defined**





# Accuracy and stability

The Suliciu solver exactly resolved **contact discontinuities**.

Under the following **subcharacteristic condition** on relaxation speed  $a$

$$a^2 \geq \rho B_3^2 + \rho \max(a_e^2, a_i^2), \quad a_\alpha = \sqrt{\frac{\gamma_\alpha p_\alpha}{\rho_\alpha}},$$

- It preserves positivity of densities and temperatures,
- It satisfies a discrete entropy inequality.

# Implicit proof : monoT Euler case

We use Riemann invariants

$$\varphi(\tau, \varepsilon, \pi) = \pi + a^2 \tau$$

$$\phi(\tau, \varepsilon, \pi) = \varepsilon - \frac{\pi^2}{2a^2}$$

Under subcharacteristic condition, we can define the following change of variable

$$\Theta(\tau, \varepsilon) = \begin{pmatrix} \varphi(\tau, \varepsilon, p(\tau, \varepsilon)) \\ \phi(\tau, \varepsilon, p(\tau, \varepsilon)) \end{pmatrix}, \quad \Theta^{-1}(X, Y) = \begin{pmatrix} \bar{\tau}(X, Y) \\ \bar{\varepsilon}(X, Y) \end{pmatrix}$$

We define the l'extended entropy  $\mathcal{S}$  from the initial entropy  $s$  :

$$\mathcal{S}(\tau, \varepsilon, \pi) = s(\bar{\tau}(\varphi(\tau, \varepsilon, \pi), \phi(\tau, \varepsilon, \pi)), \bar{\varepsilon}(\varphi(\tau, \varepsilon, \pi), \phi(\tau, \varepsilon, \pi)))$$

At equilibrium,

$$\begin{aligned} \mathcal{S}(\tau, \varepsilon, p(\tau, \varepsilon)) &= s(\bar{\tau}(\Theta(\tau, \varepsilon)), \bar{\varepsilon}(\Theta(\tau, \varepsilon))) \\ &= s(\Theta^{-1} \circ \Theta(\tau, \varepsilon)) \\ &= s(\tau, \varepsilon) \end{aligned}$$

Moreover, we can prove that  $\pi = p$  is the unique maximum de  $\mathcal{S}$ .

# Implicit proof : bitemperature MHD system

## Cas monotempérature

$$\varphi(\tau, \varepsilon, \pi) = \pi + a^2 \tau$$

$$\phi(\tau, \varepsilon, \pi) = \varepsilon - \frac{\pi^2}{2a^2}$$

Sous condition sous caractéristique, on peut définir le changement de variable

$$\Theta(\tau, \varepsilon) = \begin{pmatrix} \varphi(\tau, \varepsilon, \rho) \\ \phi(\tau, \varepsilon, \rho) \end{pmatrix}$$

$$\Theta^{-1}(X, Y) = \begin{pmatrix} \bar{\tau}(X, Y) \\ \bar{\varepsilon}(X, Y) \end{pmatrix}$$

Résultat connu : la fonction  $S : \Sigma \mapsto S(\Sigma)$  définie par

$$S(\Sigma) = s(\bar{\tau}(\varphi(\Sigma), \phi(\Sigma)), \bar{\varepsilon}(\varphi(\Sigma), \phi(\Sigma)))$$

avec  $\Sigma = (\tau, \varepsilon, \pi)$  est une entropie étendue.

## Cas bitempérature TM

$$\varphi_e(\tau, \varepsilon_e, B_3, \pi) = \pi + c_e B_3^2/2 + a^2 c_e \tau$$

$$\phi_e(\tau, \varepsilon_e, B_3, \pi) = \varepsilon_e + \tau B_3^2/2 - \frac{(\pi + c_e B_3^2/2)^2}{2(c_e a)^2}$$

$$\psi_e(\tau, \varepsilon_e, B_3, \pi) = \tau B_3$$

Sous condition sous caractéristique, on peut définir le changement de variable

$$\Theta(\tau, \varepsilon, B_3) = \begin{pmatrix} \varphi_e(\tau, \varepsilon, B_3, \rho) \\ \phi_e(\tau, \varepsilon, B_3, \rho) \\ \psi_e(\tau, \varepsilon, B_3, \rho) \end{pmatrix}$$

$$\Theta^{-1}(X, Y, Z) = \begin{pmatrix} \bar{\tau}(X, Y, Z) \\ \bar{\varepsilon}(X, Y, Z) \\ \bar{B}_3(X, Y, Z) \end{pmatrix}$$

Nouveau résultat : la fonction  $S : \Sigma \mapsto S(\Sigma)$  définie par

$$S(\Sigma) = s_e(\bar{\tau}(\phi(\Sigma), \varphi(\Sigma), \psi(\Sigma)), \bar{\varepsilon}_\alpha(\phi(\Sigma), \varphi(\Sigma), \psi(\Sigma))),$$

avec  $\Sigma = (\tau, \varepsilon, B_3, \pi)$  est une entropie étendue.

## Numerical results

# Test with smooth analytical solution

Initial conditions

$$\rho(x, 0) = 1,$$

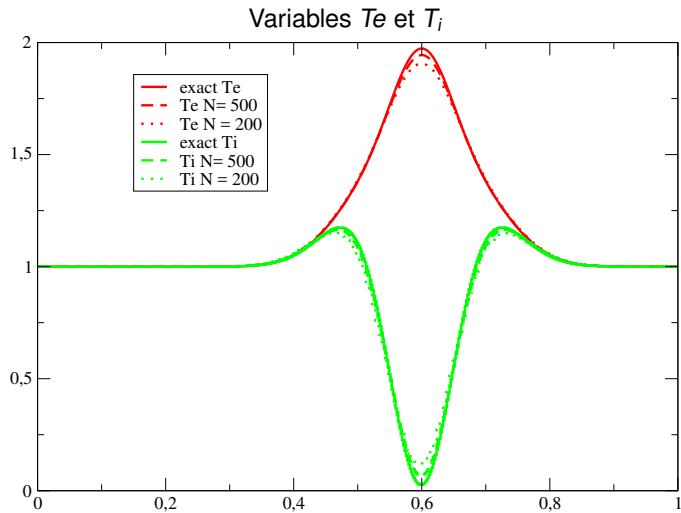
$$u_1(x, 0) = 10,$$

$$T_e(x, 0) = 1 + \exp(-200(x - 1/2)^2),$$

$$T_i(x, 0) = 2 - T_e(x, 0),$$

$$B_3(x, 0) = \exp(-50(x - 1/2)^2).$$

# Test with smooth analytical solution



# Riemann problems

Five tests about **accuracy** and **robustness**

Through rarefaction wave, contact discontinuity and shocks

Test/Variables	$\rho$	$u$	$B_3$	$T_e$	$T_i$
Test 1 <b>left</b>	1	0.75	0.8164966	0.3336667	0.3336667
Test 1 <b>right</b>	0.125	0	0.2581989	0.2669333	0.2669333
Test 2 <b>left</b>	1	-2	0.5163978	0.1334667	0.1334667
Test 2 <b>right</b>	1	2	0.5163978	0.1334667	0.1334667
Test 3 <b>left</b>	1	0	14.142136	100.10000	100.1
Test 3 <b>right</b>	1	0	0.2581989	0.0333667	0.0333667
Test 4 <b>left</b>	5.9999924	19.5975	17.528909	25.630859	25.630860
Test 4 <b>right</b>	5.9999242	-6.19633	5.5434646	2.5634264	2.5634266
Test 5 <b>left</b>	1	-19.5975	8.1649658	33.366665	33.366667
Test 5 <b>right</b>	1	-19.5975	0.2581989	0.0333667	0.0333667

# Riemann problems

Two tests about **accuracy** on **isolated contact discontinuities**

Test 6 <b>left</b>	1.4	0	0.8164966	0.2383333	0.2383333
Test 6 <b>right</b>	1	0	0.8164966	0.3336667	0.3336667
Test 7 <b>left</b>	1.4	0.1	0.8164966	0.2383333	0.2383333
Test 7 <b>right</b>	1	0.1	0.8164966	0.3336667	0.3336667

**Référence** : E. Toro, *Riemann Solvers and Numerical Methods for Fluid Dynamics : A Practical Introduction*, 1997.



# Comparison with an nonconservative HLL scheme

NC term :  $\boxed{-u} \partial_x \phi$

$$F_l^{\overline{\mathcal{E}^e}}(U_l, U_r) = F_{\text{HLL}}^{\overline{\mathcal{E}^e}}(U_l, U_r) \boxed{-u_l} (\phi_r - \phi_l)$$

$$F_r^{\overline{\mathcal{E}^e}}(U_l, U_r) = F_{\text{HLL}}^{\overline{\mathcal{E}^e}}(U_l, U_r) \boxed{-u_r} (\phi_r - \phi_l)$$

Terme NC :  $\boxed{+u} \partial_x \phi$

$$F_l^{\overline{\mathcal{E}^i}}(U_l, U_r) = F_{\text{HLL}}^{\overline{\mathcal{E}^i}}(U_l, U_r) \boxed{+u_l} (\phi_r - \phi_l)$$

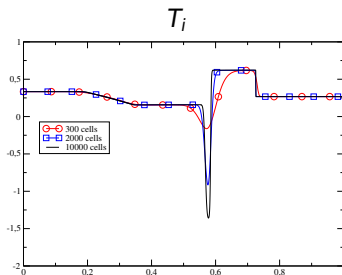
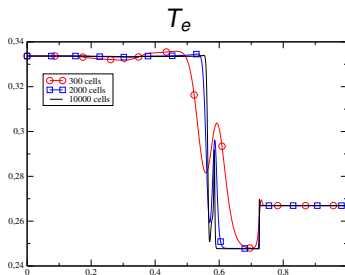
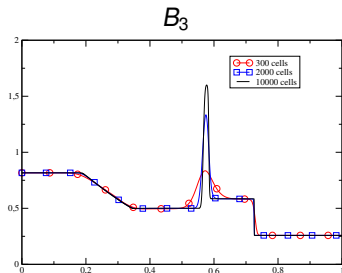
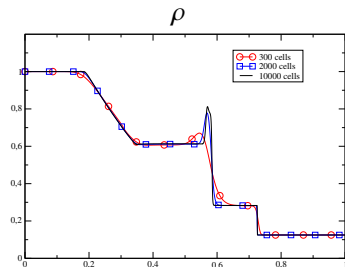
$$F_r^{\overline{\mathcal{E}^i}}(U_l, U_r) = F_{\text{HLL}}^{\overline{\mathcal{E}^i}}(U_l, U_r) \boxed{+u_r} (\phi_r - \phi_l).$$

# Numerical results

With **ncHLL**, test cases 2 and 5 show **instabilities** which ruin the simulation and fail to give a result.

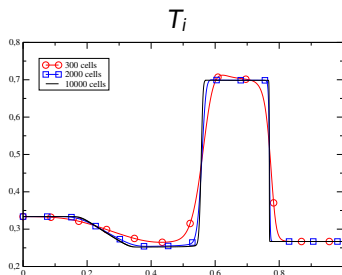
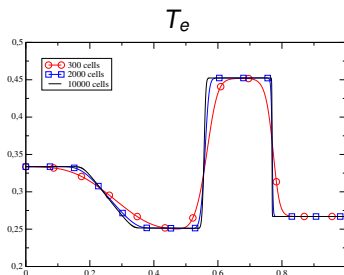
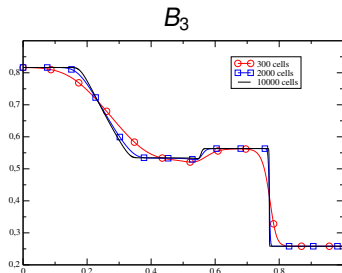
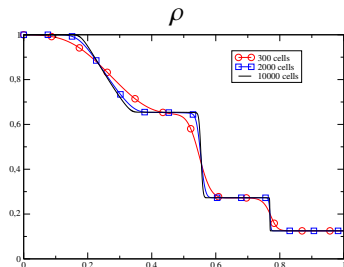
	ncHLL	Suliciu
test case 1	✓	✓
<b>test case 2</b>	<b>✗</b>	✓
test case 3	✓	✓
test case 4	✓	✓
<b>test case 5</b>	<b>✗</b>	✓
test case 6	✓	✓
test case 7	✓	✓

# Test 1 - HLL nonconservatif



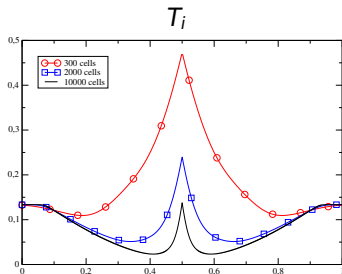
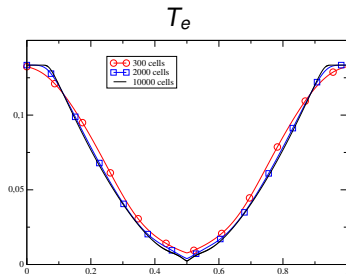
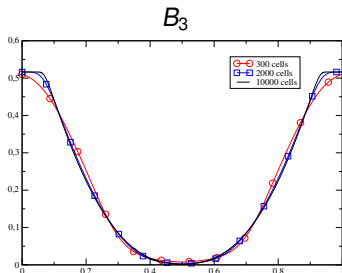
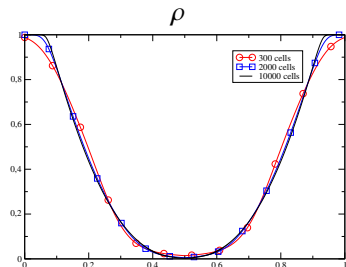
Parameter  $x_0 = 0.3$  et final time  $t = 0.2$ .

# Test 1 - Suliciu



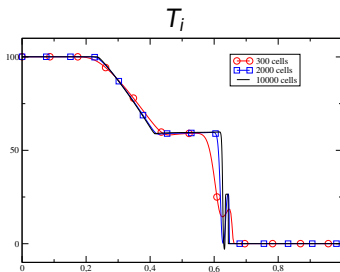
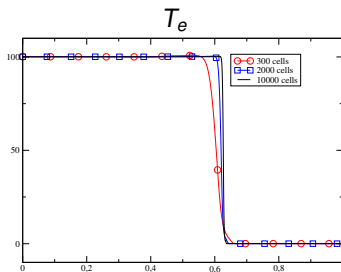
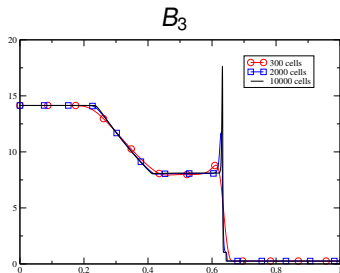
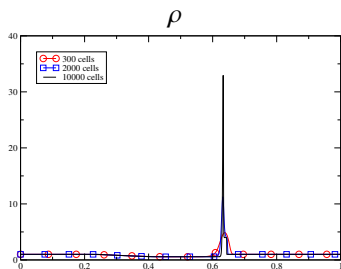
Parameter  $x_0 = 0.3$  et final time  $t = 0.2$ .

# Test 2 - Suliciu



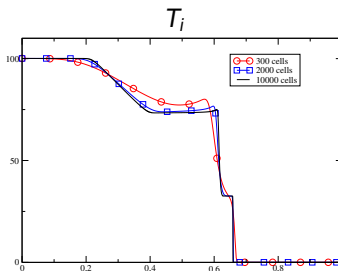
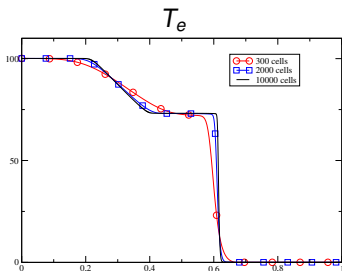
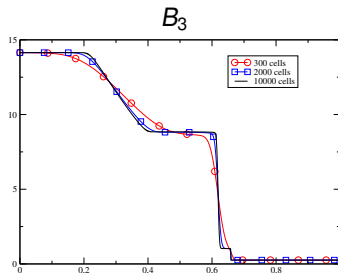
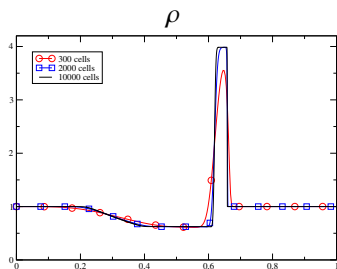
Parameter  $x_0 = 0.5$  et final time  $t = 0.15$ .

# Test 3 - HLL nonconservatif



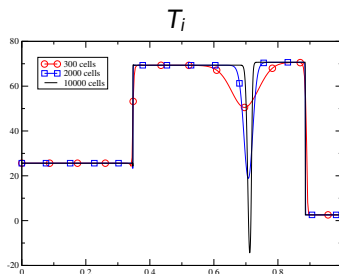
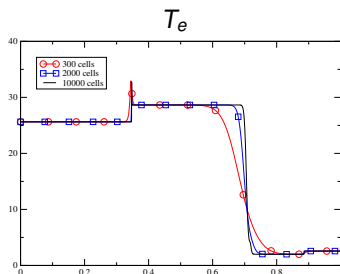
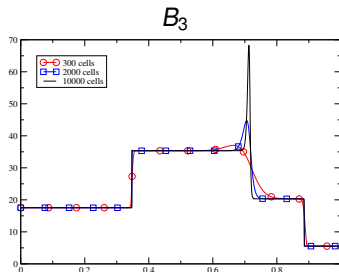
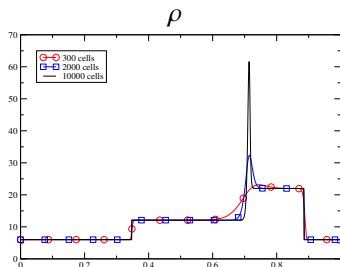
Parameter  $x_0 = 0.5$  et final time  $t = 0.012$ .

# Test 3 - Suliciu



Parameter  $x_0 = 0.5$  et final time  $t = 0.012$ .

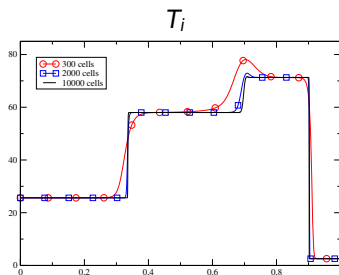
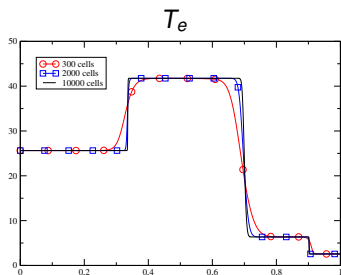
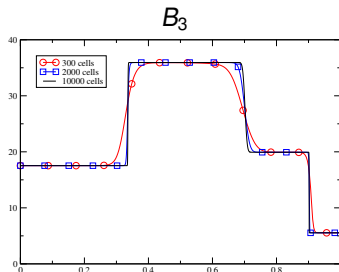
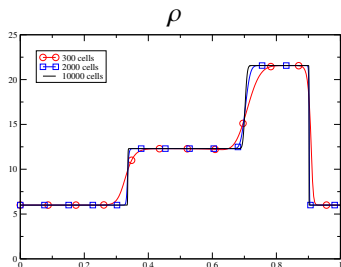
# Test 4 - HLL nonconservatif



Parameter  $x_0 = 0.4$  et final time  $t = 0.035$ .

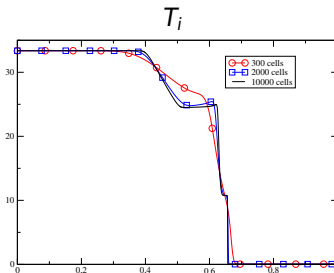
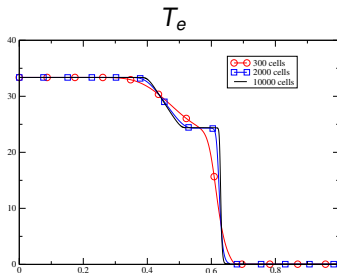
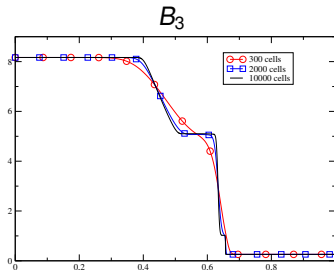
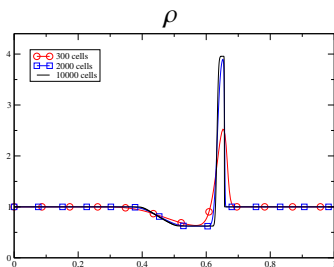


# Test 4 - Suliciu



Parameter  $x_0 = 0.4$  et final time  $t = 0.035$ .

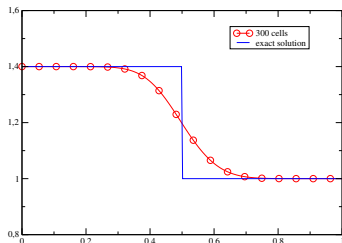
# Test 5 - Suliciu



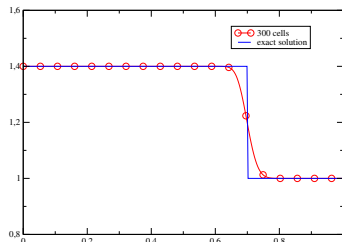
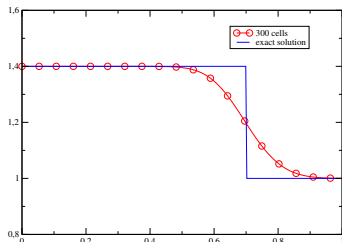
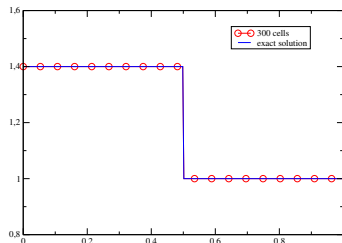
Parameter  $x_0 = 0.8$  et final time  $t = 0.012$ .

# Tests 6 et 7 : accuracy on contact discontinuities

densité HLL nonconservatif



densité Suliciu



Parameters pour le Test 6 :  $x_0 = 0.5$  et  $t = 2.0$ .

Parameters pour le Test 7 :  $x_0 = 0.3$  et  $t = 2.0$ .

**THANK YOU FOR YOUR  
ATTENTION!**