

# Understanding brain micro-structure using diffusion magnetic resonance imaging (dMRI)

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## DeFI

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![](_page_2_Picture_0.jpeg)

Timeline of our work on brain diffusion MRI

DMRI for tissue widely used 1990/2000-present, simple models

2008-2010 Formulate the mathematical problem for tissue (neurons and other cells)

2010-present Full-scale simulation and reduced model of dMRI signal due to tissue

Intra-voxel incoherent motion (IVIM) DMRI for micro-vessels started to be used 2000/2010

2013-present IVIM experiments to characterize brain micro-vessels

2015 Simulation and modeling of dMRI signal due to micro-vessels

![](_page_3_Picture_0.jpeg)

#### Outline

- 1. Brain micro-structure is complex
- 2. MRI using "diffusion encoding" to "see" micro-structure
- 3. DMRI signal due to tissue (neurons+other cells)
- 4. DMRI signal due to micro-vessels

![](_page_4_Picture_0.jpeg)

![](_page_4_Figure_2.jpeg)

Large-scale Electron Micrograph

Pink: blood vessels

Yellow: nucleoli, oligodendrocyte nuclei, and myelin

Aqua: cell bodies and dendrites.

Scale bars: a, b, 100  $\mu$ m; c–e, 10 $\mu$ m; f, 1  $\mu$ m.

Bock et al. Nature 471, 177-182 (2011)

![](_page_5_Picture_0.jpeg)

## Magnetic resonance imaging (MRI)

Non-invasive, in-vivo

![](_page_5_Picture_4.jpeg)

![](_page_5_Picture_5.jpeg)

Spatial resolution: One voxel = O(1 mm) Much bigger than micro-structure MRI signal: water proton magnetization over a volume called a voxel.

To give image contrast, magnetization is weighted by some quantity of the local tissue environment.

Contrast: (tissue structure)

- 1. Spin (water) density
- 2. Relaxation (T1,T2,T2\*)
- 3. Water displacement (diffusion) in each voxel

![](_page_6_Picture_0.jpeg)

![](_page_6_Picture_2.jpeg)

MRI contrasts Gray: cortical surface. Teal: fMRI activations Red: arteries in red Bright green: tumor

#### Yellow: white matter fiber

Diffusion Tensor and Functional MRI Fusion with Anatomical MRI for Image-Guided Neurosurgery. Sixth International Conference on Medical Image Computing and Computer-Assisted Intervention -MICCAI'03.

![](_page_7_Picture_0.jpeg)

### **Diffusion MRI**

![](_page_7_Figure_3.jpeg)

Normal axon

![](_page_7_Picture_5.jpeg)

Disintegration of myelin

![](_page_7_Picture_7.jpeg)

Disruption of axon function

Jonas: Mosby's Dictionary of Complementary and Alternative Medicine. (c) 2005, Elsevier. Diffusion MRI can measure average incoherent displacement of water in a voxel during 10s of milliseconds

Displacement of water can tell us about cellular structure

Understanding of biomechanics of cells, structure of brain

Potential clinical value

 Structure change in diseases

![](_page_8_Picture_0.jpeg)

- Standard MRI: T2 relaxation (T2 contrast) at different spatial positions of brain
- In <u>diffusion</u> MRI (recently developed) magnetization is weighted by water displacement due to Brownian motion over 10s of ms (called measured diffusion time).
- Water displacement depends on local cell environment, hindered by cell membranes.
- Right: T2 contrast does not show dendrite beading hours after stroke, diffusion weighted image (DWI) does.

![](_page_8_Picture_6.jpeg)

![](_page_8_Figure_7.jpeg)

![](_page_9_Picture_0.jpeg)

![](_page_9_Picture_2.jpeg)

**DMRI** measures **incoherent water motion** during "diffusion time" between 10-40ms.

Root mean squared displacement: 6-13 µm

**Voxel** : 2mm x 2mm x 2 mm.

![](_page_10_Picture_0.jpeg)

#### Goal: quantify dMRI contrast in terms of tissue micro-structure

![](_page_10_Picture_3.jpeg)

This problem difficult because:

- Dendrites (trees) and extra-cellular (EC) space (complement of <u>densely</u> <u>packed</u> dendrites) are <u>anisotropic</u>, <u>numerically lower dimensional</u> (dendrites 1 dim, EC 2 dim).
- 2. Multiple scales (5 orders of magnitude difference).

Extra-cellular			
space thickness	Dendrite radius	Soma diameter	DMRI voxel
10-30nm	0.5-0.9 μm	1-10µm	2mm
	·	•	

3. Cell membranes are permeable to water. Cells must be coupled together.

![](_page_11_Picture_0.jpeg)

#### Simple (original) model of dMRI Brain: 70 percent water Brownian motion of water molecules

![](_page_11_Figure_3.jpeg)

![](_page_11_Picture_4.jpeg)

Mean-squared displacement Can be obtained by dMRI

$$u(\vec{x}, t, |\vec{x}_0) = \frac{e^{-\frac{\left\|\vec{x} - \vec{x}_0\right\|^2}{4\pi Dt}}}{(4\pi Dt)^{\frac{d}{2}}}$$

$$MSD = \int u(\vec{x}, t, |\vec{x}_0) (\vec{x} - \vec{x}_0)^2 dx = 2dDt$$

![](_page_12_Picture_0.jpeg)

## How diffusion MRI assigns contrast to displacement

![](_page_12_Figure_3.jpeg)

![](_page_13_Picture_0.jpeg)

![](_page_13_Figure_2.jpeg)

![](_page_14_Picture_0.jpeg)

$$u(\mathbf{x}, t, |\mathbf{x}_{0}) = \frac{e^{-\frac{||\mathbf{x}-\mathbf{x}_{0}||^{2}}{4Dt}}}{(4\pi Dt)^{\frac{3}{2}}}$$

$$S(b) = \int_{\mathbf{x}\in V} \int_{\mathbf{x}_{0}\in V} u(\mathbf{x}, \Delta + \delta |\mathbf{x}_{0}) e^{i\gamma\delta \mathbf{g}\cdot(\mathbf{x}(\Delta+\delta)-\mathbf{x}(0))} d\mathbf{x} d\mathbf{x}_{0}$$
Experimental parameters
$$g \Delta, \delta \text{ can be varied}$$

$$ADC \equiv -\frac{d}{db} \log(S(b)):$$

$$dapparent diffusion coefficient''$$

$$u(\mathbf{x}, \Delta + \delta |\mathbf{x}_{0}) e^{i\gamma\delta \mathbf{g}\cdot(\mathbf{x}(\Delta+\delta)-\mathbf{x}(0))} d\mathbf{x} d\mathbf{x}_{0}$$

$$= e^{-D\gamma^{2}\delta^{2}||\mathbf{g}||^{2}(\Delta-\frac{\delta}{3})}$$

$$b(\mathbf{g}, \Delta, \delta) \equiv \gamma^{2}\delta^{2}||\mathbf{g}||^{2}(\Delta-\frac{\delta}{3}),$$

$$MSD/(2\Delta) = ADC$$
Brain gray matter: ADC around 10<sup>-3</sup> mm<sup>2</sup>/s Root MSD: 6-13 µm

Fitted at every voxel

![](_page_15_Picture_0.jpeg)

## Diffusion is not Gaussian in biological tissues (In each voxel) $\frac{S}{d} \neq e^{-(ADC)b}$

 $S_0$ 

Human visual cortex (Le Bihan et al. PNAS 2006).

![](_page_15_Figure_4.jpeg)

Log plot not a straight line.

Simple model is "wrong"

Physicists try a different simple model

$$\frac{S}{S_0} = f_{fast}e^{-D_{fast}b} + f_{slow}e^{-D_{slow}b}.$$

$$f_{fast} = 65.9\%, f_{slow} = 34.1\%$$

 $D_{fast} = 1.39 \ 10^{-3} \ mm^{2}/s,$  $D_{slow} = 3.25 \ 10^{-4} \ mm^{2}/s$ 

![](_page_16_Picture_0.jpeg)

 $\Omega^i$ ,  $D^i$ 

#### **Reference model: Bloch-Torrey PDE**

$$\frac{\partial M^{j}(\mathbf{x},t|\mathbf{g})}{\partial t} = i \gamma f(t)(\mathbf{g} \cdot \mathbf{x}) M^{j}(\mathbf{x},t|\mathbf{g}) + \nabla \cdot \left( D^{j} \nabla M^{j}(\mathbf{x},t|\mathbf{g}) \right), \mathbf{x} \in \Omega^{j} \ .$$
PDE with interface condition between cells and the extra-cellular space
$$\frac{D^{j} \nabla M^{j}(\mathbf{x},t|\mathbf{g}) \cdot \mathbf{n}^{j}(\mathbf{x}) = -D^{k} \nabla M^{k}(\mathbf{x},t|\mathbf{g}) \cdot \mathbf{n}^{k}(\mathbf{x}), \quad \mathbf{x} \in \Gamma^{jk},$$

$$D^{j} \nabla M^{j}(\mathbf{x},t|\mathbf{g}) \cdot \mathbf{n}^{j}(\mathbf{x}) = \kappa \left( M^{j}(\mathbf{x},t,|\mathbf{g}) - M^{k}(\mathbf{x},t|\mathbf{g}) \right), \quad \mathbf{x} \in \Gamma^{jk},$$

$$S(\mathbf{g}, T_{end}) = \sum_{j} \int_{\mathbf{x} \in \Omega^{j}} M^{j}(\mathbf{x},t|\mathbf{g}) d\mathbf{x} \approx \exp(-ADC \ b_{experi}).$$

$$M: \text{ magnetization } g: \text{ magnetic field gradient } T_{end}: \text{ diffusion time}$$

From signal, want to quantify cell geometry and membrane permeability.

 $\Omega^e, D^e$ 

κ<sup>ie</sup>

![](_page_17_Picture_0.jpeg)

1. Numerical simulation of diffusion MRI signals using an adaptive timestepping method, J.-R. Li, D. Calhoun, C. Poupon, D. Le Bihan. Physics in Medicine and Biology, 2013.

2. A finite elements method to solve the Bloch-Torrey equation applied to diffusion magnetic resonance imaging, D.V. Nguyen, J.R. Li, D. Grebenkov, D. Le Bihan, Journal of Computational Physics, 2014.

![](_page_17_Figure_4.jpeg)

![](_page_18_Picture_0.jpeg)

## On-going work (2013 $\rightarrow$ ) Mathematical analysis

2012: Obtained macroscopic (ODE) model using homogenization Valid in long diffusion time regime.

More relevant to brain dMRI: 2013: Look for macroscopic model valid at <u>wide range of diffusion times</u>

PhD Simona Schiavi 2013-present (co-directed w. H. Haddar)

![](_page_18_Figure_6.jpeg)

![](_page_19_Picture_0.jpeg)

Timeline of our work on brain diffusion MRI

(DMRI for micro-vessels started to be used 2000/2010, simple models)

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2015 Simulation and modeling of dMRI signal due to micro-vessels

![](_page_20_Picture_0.jpeg)

#### The cerebro-vasculature

![](_page_20_Picture_3.jpeg)

Dragos A. Nita Neurology 2012;79:e10

![](_page_21_Picture_0.jpeg)

![](_page_21_Figure_2.jpeg)

The cortical angiome: an interconnected vascular network with noncolumnar patterns of blood flow

Blinder et al. Nature Penetrating Neuroscience 2013

![](_page_22_Picture_0.jpeg)

![](_page_22_Figure_2.jpeg)

![](_page_22_Figure_3.jpeg)

![](_page_23_Picture_0.jpeg)

![](_page_23_Figure_2.jpeg)

Jingpeng Wu, Yong He, Zhongqin Yang, Congdi Guo, Qingming Luo, Wei Zhou, Shangbin Chen, Anan Li, Benyi Xiong, Tao Jiang, Hui Gong NeuroImage 2014

![](_page_24_Picture_0.jpeg)

![](_page_24_Figure_2.jpeg)

![](_page_25_Picture_0.jpeg)

multislice,Sperf fstar >= 30 percent '10 multislice,Sperf dstar >= 0.2 mm <sup>2</sup>/s vin -50 -70 - 80

![](_page_26_Picture_0.jpeg)

![](_page_26_Figure_2.jpeg)

Simple model: suppose there are two pools of blood: a « slow » pool (0.2 < v < 4.2 mm/s)a « fast » pool (4.2 < v < 15 mm/s).

![](_page_27_Picture_0.jpeg)

## Numerical simulations of microvascular networks

#### Step 1

Create a microvascular network consisting of capillary segments: (length L, direction  $\vec{e}$  and blood flow velocity v)

#### Step 2

Calculate the IVIM signal coming from this network using:

$$\frac{S}{S_0} = e^{-i\varphi} \ \varphi = \gamma \int_0^{TE} \vec{x}(t) \cdot \vec{G}(t) dt$$

- $\varphi$  phase of the MRI signal
- $\vec{x}(t)$  spin position vector
- $\vec{G}(t)$  encoding gradient vector

## Step 3

Generate simulated signals for Gaussian distributions of lengths (L = 50 ± 50 µm [1]) and velocities ( $v \pm \sigma_v$ ), with v varying between 0.2 and 15 mm/s and  $\sigma_v$  between 0.05 and 1

![](_page_27_Picture_15.jpeg)

![](_page_27_Picture_16.jpeg)

![](_page_28_Picture_0.jpeg)

#### Two pools of blood:

### Interpretation of data

$$F_{IVIM} = f_{slow}e^{-bD_{slow}^*} + f_{fast}e^{-bD_{fast}^*}$$

- ⇒A « fast » pool: flow within vessels with significant sizes relative to the voxel size
- $\Rightarrow v_{fast} = 7.92 \pm 3.95$  mm/s, coherent with medium size vessels such as penetrating arterioles or venules [1]
- ⇒A « slow » pool: flow in small vessels and capillaries (classical IVIM model) ⇒ $D^*_{slow}$  15 times smaller than  $D^*_{fast}$ ⇒ $v_{slow}$  = 1.72 ± 0.30 mm/s, coherent with capillary bed vessels [2]

arterioles Deep microvessels

Credit: Nishimura N., 2007, PNAS

[1] Linninger A. A., 2013, Ann Biomed Eng, [2] Unekawa M., 2010, Brain Res

Surface arterioles

Penetrating

![](_page_29_Picture_0.jpeg)

![](_page_29_Picture_2.jpeg)

## Need more sophisticated simulations to explain data

In the brain cortex 5 percent blood volume.

Blood contains red blood cells (50 percent volume) and plasma (50 percent volume)

Red blood cells contain 70 percent water Plasma is 92 percent water.

![](_page_30_Picture_0.jpeg)

## Ready for some fluids simulations to get average blood water displacement during 10s of milliseconds!

## Thank you! (Welcome any suggestions and ideas)