Nodal finite volumes for hyperbolic systems with source terms on unstructured meshes

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Outline

Mathematical and physical context

AP scheme for the P_1 model

Extension to the Euler model







Mathematic and physical context







Stiff hyperbolic systems

Stiff hyperbolic system with source terms:

$$\partial_t \mathbf{U} + \frac{1}{\varepsilon} \partial_x F(\mathbf{U}) + \frac{1}{\varepsilon} \partial_y G(\mathbf{U}) = \frac{1}{\varepsilon} S(\mathbf{U}) - \frac{\sigma}{\varepsilon^2} R(\mathbf{U}), \ \mathbf{U} \in R^n$$

with $\varepsilon \in \left]0,1\right]$ et $\sigma > 0$.

Subset of solutions given by the balance between the source terms and the convective part:

□ **Diffusion solutions** for $\varepsilon \rightarrow 0$ and $S(\mathbf{U}) = 0$:

$$\partial_t \mathbf{V} - \operatorname{div} \left(K(\nabla \mathbf{V}, \sigma) \right) = 0, \quad \mathbf{V} \in \operatorname{Ker} R.$$

□ Steady states for $\sigma = 0$ et $\varepsilon \rightarrow 0$:

$$\partial_x F(\mathbf{U}) + \partial_y G(\mathbf{U}) = S(\mathbf{U}).$$

Applications: biology, neutron transport, fluid mechanics, plasma physics, Radiative hydrodynamic for inertial fusion (hydrodynamic + linear transport of photon).



Well-Balanced schemes

- Discretization of physical steady states is important (Lack at rest for Shallow water equations, hydrostatic equilibrium for astrophysical flows ..)
- Classical scheme: the physical steady states or a good discretization of the steady states are not the equilibriums of the scheme.
- Consequence: Spurious numerical velocities larger than physical velocities for nearly or exact uniform flows.

WB scheme: definitions

- **Exact Well-Balanced scheme**: is a scheme exact for continuous steady-states.
- □ Well-Balanced scheme: is a scheme exact for discrete steady-states at the interfaces.

- For shallow water model: in general the schemes are exact WB schemes.
- For Euler model: in general the schemes are WB schemes.



Schémas "Asymptotic preserving"

P₁ model:

$$\begin{cases} \partial_t E + \frac{1}{\epsilon} \partial_x F = 0, \\ \partial_t F + \frac{1}{\epsilon} \partial_x E = -\frac{\sigma}{\epsilon^2} F, \end{cases}$$



Figure: AP diagram

$$\longrightarrow \partial_t E - \partial_x \left(\frac{1}{\sigma} \partial_x E\right) = 0.$$

- Consistency of **Godunov-type** schemes: $O(\frac{\Delta x}{\varepsilon} + \Delta t)$.
- CFL condition: $\Delta t (\frac{1}{\Delta x \varepsilon} + \frac{\sigma}{\varepsilon^2}) \leq 1.$
- Consistency of AP schemes: $O(\Delta x + \Delta t)$.

• CFL condition:

$$\Delta t \left(\frac{1}{\Delta x \varepsilon + \frac{\Delta x^2}{\sigma}} \right) \leq 1.$$

• AP vs non AP schemes: Important reduction of CPU cost.

• AP schemes are obtained plugging the source term into the fluxes (WB technic).



- Jin-Levermore scheme
- **Principle**: plug the balance law $\partial_x E = -\frac{\sigma}{\varepsilon}F + O(\varepsilon^2)$ in the fluxes.





Jin-Levermore scheme

Principle: plug the balance law $\partial_x E = -\frac{\sigma}{\epsilon}F + O(\epsilon^2)$ in the fluxes.

we write the relations

$$\left\{ \begin{array}{l} E(x_j) = E(x_{j+\frac{1}{2}}) + (x_j - x_{j+\frac{1}{2}})\partial_x E(x_{j+\frac{1}{2}}), \\ E(x_{j+1}) = E(x_{j+\frac{1}{2}}) + (x_{j+1} - x_{j+\frac{1}{2}})\partial_x E(x_{j+\frac{1}{2}}) \end{array} \right.$$





Jin-Levermore scheme

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we write the relations

$$\begin{cases} E(x_j) = E(x_{j+\frac{1}{2}}) - (x_j - x_{j+\frac{1}{2}})\frac{\sigma}{e}F(x_{j+\frac{1}{2}}), \\ E(x_{j+1}) = E(x_{j+\frac{1}{2}}) - (x_{j+1} - x_{j+\frac{1}{2}})\frac{\sigma}{e}F(x_{j+\frac{1}{2}}). \end{cases}$$





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We couple these relations with the fluxes

$$\begin{cases} F_j + E_j = F_{j+\frac{1}{2}} + E_{j+\frac{1}{2}}, \\ F_{j+1} - E_{j+1} = F_{j+\frac{1}{2}} - E_{j+\frac{1}{2}}. \end{cases}$$





Jin-Levermore scheme

• **Principle**: plug the balance law $\partial_x E = -\frac{\sigma}{\varepsilon}F + O(\varepsilon^2)$ in the fluxes.

we write the relations

$$\begin{cases} E(x_j) = E(x_{j+\frac{1}{2}}) - (x_j - x_{j+\frac{1}{2}}) \frac{\sigma}{\epsilon} F(x_{j+\frac{1}{2}}), \\ E(x_{j+1}) = E(x_{j+\frac{1}{2}}) - (x_{j+1} - x_{j+\frac{1}{2}}) \frac{\sigma}{\epsilon} F(x_{j+\frac{1}{2}}), \\ \begin{cases} F_j + E_j = F_{j+\frac{1}{2}} + E_{j+\frac{1}{2}} + \frac{\sigma\Delta x}{2\epsilon} F_{j+\frac{1}{2}}, \\ F_{j+1} - E_{j+1} = F_{j+\frac{1}{2}} - E_{j+\frac{1}{2}} + \frac{\sigma\Delta x}{2\epsilon} F_{j+\frac{1}{2}}. \end{cases} \end{cases}$$





- Jin-Levermore scheme
- Principle: plug the balance law $\partial_x E = -\frac{\sigma}{\epsilon}F + O(\epsilon^2)$ in the fluxes.

Jin Levermore scheme:

$$\frac{E_{j}^{n+1}-E_{j}^{n}}{\Delta t} + \frac{M}{\frac{E_{j+1}^{n}-E_{j-1}^{n}}{2\epsilon\Delta x}} - \frac{M}{\frac{E_{j+1}^{n}-2E_{j}^{n}+E_{j-1}^{n}}{2\epsilon\Delta x}} = 0,$$

$$\frac{E_{j}^{n+1}-E_{j}^{n}}{\Delta t} + \frac{E_{j+1}^{n}-E_{j-1}^{n}}{2\epsilon\Delta x} - \frac{E_{j+1}^{n}-2E_{j}^{n}+E_{j-1}^{n}}{2\epsilon\Delta x} + \frac{\sigma}{\epsilon_{j}^{2}}E_{j}^{n} = 0$$

with $M = \frac{2\varepsilon}{2\varepsilon + \sigma \Delta x}$.



- Jin-Levermore scheme
- Principle: plug the balance law $\partial_x E = -\frac{\sigma}{\varepsilon}F + O(\varepsilon^2)$ in the fluxes.

Gosse-Toscani scheme:

$$\begin{cases} \frac{E_j^{n+1}-E_j^n}{\Delta t} + M\frac{F_{j+1}^n - F_{j-1}^n}{2\epsilon\Delta x} - M\frac{E_{j+1}^n - 2E_j^n + E_{j-1}^n}{2\epsilon\Delta x} = 0, \\ \frac{F_j^{n+1} - F_j^n}{\Delta t} + M\frac{E_{j+1}^n - E_{j-1}^n}{2\epsilon\Delta x} - M\frac{F_{j+1}^n - 2F_j^n + F_{j-1}^n}{2\epsilon\Delta x} + M\frac{\sigma}{\epsilon^2}F_j^n = 0, \end{cases}$$

avec $M = \frac{2\epsilon}{2\epsilon + \sigma\Delta x}.$

- consistency error for the lin-Levermore scheme:
 - $\Box \quad \text{first equation:} \\ O\left(\Delta x^2 + \varepsilon \Delta x + \Delta t\right),$
 - \Box second equation:

$$O\left(\frac{\Delta x^2}{\varepsilon} + \Delta x + \Delta t\right).$$

- Explicit CFL: $\Delta t \left(\frac{1}{\Delta x \varepsilon} + \frac{\sigma}{\varepsilon^2} \right) \leq 1.$
- Semi-implicit CFL: $\Delta t \left(\frac{1}{\Delta x \varepsilon}\right) \leq 1$.

- Principle of GT scheme: JL-scheme with the source term $\frac{1}{2}(F_{j+\frac{1}{2}} + F_{j-\frac{1}{2}})$ gives the Gosse-Toscani scheme.
- Consistency error of the **Gosse-Toscani** scheme: $O(\Delta x + \Delta t)$.
- Explicit CFL: $\Delta t \left(\frac{1}{\Delta x \varepsilon}\right) \leq 1$.
- Semi-implicit CFL : $\Delta t \left(\frac{1}{\Delta x \epsilon + \Delta x^2}\right) \leq 1.$



Numerical example

Validation test for AP scheme: the data are E(0, x) = G(x) with G(x) a Gaussian F(0, x) = 0 and $\sigma = 1$, $\varepsilon = 0.001$.



Scheme	L ¹ error	CPU time		
Godunov, 10000 cells	0.0366	1485m4.26s		
Godunov, 500 cells	0.445	0m24.317s		
AP, 500 cells	0.0001	0m15.22s		
AP, 50 cells	0.0065	0m0.054s		



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Non complete state of art

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Why unstructured meshes ?

- Applications : coupling between radiation and hydrodynamic
- In some hydrodynamic codes: Lagrangian or ALE scheme cell-centered for multi-material problems.
- Example of meshes obtained using a ALE code.
- Aim: Design and analyze AP cell-centered for linear transport on general meshes.





Schémas "Asymptotic preserving" 2D

Classical extension in 2D of the Jin-Levermore scheme : modify the upwind fluxes (1D fluxes write in the normal direction) plugging the steady states in the fluxes.



I_{jk} and \mathbf{n}_{jk} the normal and length associated with the edge $\partial \Omega_{jk}$.

Asymptotic limit of the scheme:

$$\mid \Omega_j \mid \partial_t E_j(t) - \frac{1}{\sigma} \sum_k l_{jk} \frac{E_k^n - E_j^n}{d(\mathbf{x}_j, \mathbf{x}_k)} = 0.$$

■ $||P_h^0 - P_h|| \rightarrow 0$ only on strong geometrical conditions.

■ These AP schemes **do not converge** on 2D general meshes $\forall \epsilon$.





Example of unstructured meshes







AP scheme for the P_1 model







Nodal scheme : linear case

Linear case: P₁ model

$$\begin{cases} \partial_t E + \frac{1}{\varepsilon} \operatorname{div}(\mathbf{F}) = 0, \\ \partial_t \mathbf{F} + \frac{1}{\varepsilon} \nabla E = -\frac{\sigma}{\varepsilon^2} \mathbf{F}. \end{cases} \longrightarrow \partial_t E - \operatorname{div}\left(\frac{1}{\sigma} \nabla E\right) = 0. \end{cases}$$

Idea:

Nodal finit evolume methods for P_1 model + AP and WB method.

Nodal schemes:

The fluxes are localized at the nodes of the mesh (for the classical scheme this is at the edge).

Nodal geometrical quantities $\mathbf{C}_{jr} = \nabla_{\mathbf{x}_r} |\Omega_j|$.







2D AP schemes

Nodal AP scheme

$$\mid \Omega_j \mid \partial_t E_j(t) + \frac{1}{\varepsilon} \sum_r (\mathbf{F}_r, \mathbf{C}_{jr}) = 0,$$

$$\mid \Omega_j \mid \partial_t \mathbf{F}_j(t) + \frac{1}{\varepsilon} \sum_r \mathbf{E} \mathbf{c}_{jr} = \mathbf{S}_j.$$

Classical nodal fluxes:

$$\begin{cases} \mathbf{E}\mathbf{c}_{jr} - \mathbf{E}_j \mathbf{C}_{jr} = \widehat{\alpha}_{jr} (\mathbf{F}_j - \mathbf{F}_r), \\ \sum_j \mathbf{E}\mathbf{c}_{jr} = \mathbf{0}, \end{cases}$$

with $\widehat{\alpha}_{jr} = \frac{\mathbf{C}_{jr} \otimes \mathbf{C}_{jr}}{\|\mathbf{C}_{jr}\|}.$

New fluxes obtained plugging steady-state $\nabla E = -\frac{\sigma}{\varepsilon} \mathbf{F}$ in the fluxes:

$$\begin{cases} \mathbf{E}\mathbf{c}_{jr} - E_{j}\mathbf{C}_{jr} = \widehat{\alpha}_{jr}(\mathbf{F}_{j} - \mathbf{F}_{r}) - \frac{\sigma}{\varepsilon}\widehat{\beta}_{jr}\mathbf{F}_{r}, \\ \left(\sum_{j}\widehat{\alpha}_{jr} + \frac{\sigma}{\varepsilon}\sum_{j}\widehat{\beta}_{jr}\right)\mathbf{F}_{r} = \sum_{j}E_{j}\mathbf{C}_{jr} + \sum_{j}\widehat{\alpha}_{jr}\mathbf{F}_{j} \end{cases}$$

with $\widehat{eta}_{jr} = \mathbf{C}_{jr} \otimes (\mathbf{x}_r - \mathbf{x}_j).$

Source term: (1) $\mathbf{S}_j = -\frac{\sigma}{\epsilon^2} |\Omega_j| \mathbf{F}_j$ ou (2) $\mathbf{S}_j = -\frac{\sigma}{\epsilon^2} \sum_r \hat{\beta}_{jr} \mathbf{F}_r$, $\sum_r \hat{\beta}_{jr} = \hat{l}_d |\Omega_j|$.





Time AP scheme

• New formulation of the scheme + semi discrete scheme.

Local semi-implicit scheme

$$| \Omega_j | \frac{E_j^{n+1} - E_j^n}{\triangle t} + \frac{1}{\varepsilon} \sum_r (M_r \mathbf{F}_r, \mathbf{C}_{jr}) = 0,$$

$$| \Omega_j | \frac{\mathbf{F}_j^{n+1} - \mathbf{F}_j^n}{\triangle t} + \frac{1}{\varepsilon} \sum_r \mathbf{E}_{jr} = -\frac{1}{\varepsilon} \left(\sum_r \hat{\alpha}_{jr} (\hat{I}_d - M_r) \right) \mathbf{F}_j^{n+1}.$$

with

$$\begin{cases} \mathbf{E}\mathbf{c}_{jr} - E_{j}\mathbf{C}_{jr} = \widehat{\alpha}_{jr}\mathbf{M}_{r}(\mathbf{F}_{j} - \mathbf{F}_{r}), \\ \left(\sum_{j}\widehat{\alpha}_{jr}\right)\mathbf{F}_{r} = \sum_{j}E_{j}\mathbf{C}_{jr} + \sum_{j}\widehat{\alpha}_{jr}\mathbf{F}_{j}. \\ \mathbf{M}_{r} = \left(\sum_{j}\widehat{\alpha}_{jr} + \frac{\sigma}{\varepsilon}\sum_{j}\widehat{\beta}_{jr}\right)^{-1}\left(\sum_{j}\widehat{\alpha}_{jr}\right) \end{cases}$$

- The scheme is stable under a CFL condition which is the sum to the parabolic and hyperbolic CFL conditions (verified numerically).
- The full implicit version is unconditionally stable.





Assumptions for the convergence proof

Geometrical assumptions

$$\quad (\mathbf{u}, \left(\sum_{r} \frac{\mathbf{C}_{jr} \otimes \mathbf{C}_{jr}}{|\mathbf{C}_{jr}|}\right) \mathbf{u}) \geq \beta h(\mathbf{u}, \mathbf{u})$$

•
$$(\mathbf{u}, \left(\sum_{j} \frac{\mathbf{C}_{jr} \otimes \mathbf{C}_{jr}}{|\mathbf{C}_{jr}|}\right) \mathbf{u}) \ge \gamma h(\mathbf{u}, \mathbf{u}),$$

•
$$(\mathbf{u}, (\sum_{j} \mathbf{C}_{jr} \otimes (\mathbf{x}_{r} - \mathbf{x}_{j})) \mathbf{u}) \ge \alpha h^{2}(\mathbf{u}, \mathbf{u}).$$

- First and second assumptions: true on all non degenerated meshes.
- Last assumption: sufficient (not necessary) conditions on the meshes obtained.
- Example for triangles: all the angles must be larger that 12 degrees.

Assumption on regularity and initial data

F
$$(t = 0, \mathbf{x}) = -\frac{\varepsilon}{\sigma} \nabla E(t = 0, \mathbf{x})$$

- Regularity for exact data: $\mathbf{V}(t, \mathbf{x}) \in H^4(\Omega)$
- Regularity for initial data of the scheme: $\mathbf{V}_h(t=0,\mathbf{x})\in L^2(\Omega)$





Uniform convergence in space

- Naive convergence estimate : $||P_h^{\varepsilon} P^{\varepsilon}||_{naive} \le C\varepsilon^{-b}h^c$
- **Idea**: use triangular inequalities and AP diagram (Jin-Levermore-Golse).

 $||P_h^{\varepsilon} - P^{\varepsilon}||_{L^2} \leq \min(||P_h^{\varepsilon} - P^{\varepsilon}||_{\textit{naive}}, ||P_h^{\varepsilon} - P_h^{0}|| + ||P_h^{0} - P^{0}|| + ||P^{\varepsilon} - P^{0}||)$



We obtain:

$$||P_h^{\varepsilon} - P^{\varepsilon}||_{L^2} \leq C \min(\varepsilon^{-b}h^c, \varepsilon^a + h^d + \varepsilon^e))$$

Comparing ε and $\varepsilon_{threshold} = h^{\frac{ac}{a+b}}$ we obtain the final estimation:

$$||P_h^{\varepsilon} - P^{\varepsilon}||_{L^2} \le h^{\frac{ac}{a+b}}$$





Limit diffusion scheme

Limit diffusion scheme (P_h^0) :

$$\begin{cases} &| \Omega_j | \partial_t E_j(t) - \sum_r (\mathbf{F}_r, \mathbf{C}_{jr}) = 0, \\ &\sum_r \hat{\alpha}_{jr} \mathbf{F}_j = \sum_r \hat{\alpha}_{jr} \mathbf{F}_r, \\ &\sigma A_r \mathbf{F}_r = \sum_j E_j \mathbf{C}_{jr}, \quad A_r = -\sum_j \mathbf{C}_{jr} \otimes (\mathbf{x}_r - \mathbf{x}_j). \end{cases}$$



- **Problem**: estimation on $||P_h^{\varepsilon} P_h^0||$.
- In practice we obtain $||P_h^{\varepsilon} P_h^0|| \le C \frac{\varepsilon}{h}$ (not sufficient for the proof).

H Condition:

The Hessian matrix of the scheme P_h^0 can be upper-bounded or the error estimate $||P_h^e - P_h^0||$ can be obtained independently of the discrete Hessian matrix.



FV nodal schemes

Limit diffusion scheme

Limit diffusion scheme (P_h^0) :

$$\begin{cases} &|\Omega_{j}| \partial_{t} E_{j}(t) - \sum_{r} (\mathbf{F}_{r}, \mathbf{C}_{jr}) = 0, \\ &\sum_{r} \hat{\alpha}_{jr} \mathbf{F}_{j} = \sum_{r} \hat{\alpha}_{jr} \mathbf{F}_{r}, \\ &\sigma A_{r} \mathbf{F}_{r} = \sum_{j} E_{j} \mathbf{C}_{jr}, \quad A_{r} = -\sum_{j} \mathbf{C}_{jr} \otimes (\mathbf{x}_{r} - \mathbf{x}_{j}). \end{cases}$$



- **Problem**: estimation on $||P_h^{\varepsilon} P_h^0||$.
- In practice we obtain $||P_h^{\varepsilon} P_h^0|| \le C \frac{\varepsilon}{h}$ (not sufficient for the proof).
- Introduction of a intermediary diffusion scheme DA^ε_h.
- DA_h^{ε} : P_h^{ε} scheme with $\partial_t \mathbf{F}_j = \mathbf{0}$.
- In the previous estimate we replace P⁰_h by DA^ε_h.

H Condition:

The Hessian matrix of the scheme P_h^0 can be upper-bounded or the error estimate $||P_h^e - P_h^0||$ can be obtained independently of the discrete Hessian matrix.



Final result in space

- H condition obtained : we use P_h^0 in the estimates.
- H condition not obtained : we use DA_h^{ε} in the estimates.
- The H condition is obtained in 1D (grid uniform or not) and in 2D Cartesian grids.

Final result:

We assume that the assumptions are verified. There are some constant C > 0 such that

$$\Box \ ||P^{\varepsilon} - P_{h}^{\varepsilon}||_{\textit{naive}} \leq C_{0} \sqrt{\frac{h}{\varepsilon}} \parallel p_{0} \parallel_{H^{4}(\Omega)},$$

$$\square ||DA_h^{\varepsilon} - P^0|| \le C_1(h+\varepsilon) \parallel p_0 \parallel_{H^4(\Omega)},$$

 $\Box ||P_h^{\varepsilon} - DA_h^{\varepsilon}|| \leq C_2 \left(h^2 + \varepsilon \max\left(1, \sqrt{\varepsilon h^{-1}}\right)\right) || p_0 ||_{H^4(\Omega)},$

$$\Box ||P^{\varepsilon} - P^{0}|| \leq C_{3}\varepsilon, \qquad 0 < t \leq T.$$

and

$$\|\mathbf{V}^{\varepsilon}-\mathbf{V}_{h}^{\varepsilon}\|_{L^{2}([0,T]\times\Omega)}\leq C\min\left(\sqrt{\frac{h}{\varepsilon}},h^{2}+\varepsilon\max\left(1,\sqrt{\frac{\varepsilon}{h}}\right)+(h+\varepsilon)+\varepsilon\right)\parallel p_{0}\parallel_{H^{4}}\leq Ch^{\frac{1}{4}}.$$

Using $\varepsilon_{thresh} = h^{\frac{1}{2}}$ we prove that the worst case is $\|\mathbf{V}^{\varepsilon} - \mathbf{V}_{h}^{\varepsilon}\| \le C_{2}h^{\frac{1}{4}}$.





Time estimation

Time scheme: implicit scheme (the estimate for explicit scheme is an open question). We obtain

$$\frac{\mathbf{U}_h^{n+1} - \mathbf{U}_h^n}{\Delta t} = A_h \mathbf{U}_h^{n+1}$$

with A_h the matrix which discretized the space scheme.

Discrete stability: We have $(\mathbf{U}_h, A_h \mathbf{U}_h) \leq 0$. Consequently $\| \mathbf{U}_h^{n+1} \| \leq \| \mathbf{U}_h^n \|$

Final result for the full discrete scheme

We assume that the regularity and geometrical assumptions are verified. There is a constant $C(\mathcal{T}) > 0$ such that:

$$\|\mathbf{V}^{\varepsilon}(t_n) - \mathbf{V}^{\varepsilon}_h(t_n)\|_{L^2(\Omega)} \leq C\left(f(h,\varepsilon) + \Delta t^{\frac{1}{2}}\right) \|p_0\|_{H^4(\Omega)}.$$

Idea of proof: Stability result + Duhamel formula (B. Després).



AP scheme vs classical scheme

Test case: heat fundamental solution. Results for different P_1 scheme with $\varepsilon = 0.001$ on Kershaw mesh.



Diffusion solution



Non AP scheme

1.5

0.5

0

1.5 3 2

0.5

2

-1

-2

Uniform convergence for the P_1 model

Periodic solution for the P_1 which depend of ε .

•
$$E(t, \mathbf{x}) = (\alpha(t) + \frac{\varepsilon^2}{\sigma} \alpha'(t)) \cos(\pi x) \cos(\pi y)$$

F $(t, \mathbf{x}) = \left(-\frac{\varepsilon}{\sigma}\alpha(t)\sin(\pi x)\cos(\pi y), -\frac{\varepsilon}{\sigma}\alpha(t)\sin(\pi y)\cos(\pi x)\right)$

Convergence study for $\varepsilon = h^{\gamma}$ on random mesh.



Numerical results show that the error is homogenous to $O(h\varepsilon + h^2)$.

- Theoretical estimate that we can hope: $O((h\varepsilon)^{\frac{1}{2}} + h)$.
- Non optimal estimation in the intermediary regime.





Uniform convergence for the P_1 model

Periodic solution for the P_1 which depend of ε .

•
$$E(t, \mathbf{x}) = (\alpha(t) + \frac{\varepsilon^2}{\sigma} \alpha'(t)) \cos(\pi x) \cos(\pi y)$$

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Convergence study for $\varepsilon = h^{\gamma}$ on random mesh.



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Extension to the Euler model







Euler equation with external forces

Euler equation with gravity and friction:

$$\begin{cases} \partial_t \rho + \frac{1}{\varepsilon} \operatorname{div}(\rho \mathbf{u}) = 0, \\ \partial_t \rho \mathbf{u} + \frac{1}{\varepsilon} \operatorname{div}(\rho \mathbf{u} \otimes \mathbf{u}) + \frac{1}{\varepsilon} \nabla \rho = -\frac{1}{\varepsilon} (\rho \nabla \phi + \frac{\sigma}{\varepsilon} \rho \mathbf{u}), \\ \partial_t \rho e + \frac{1}{\varepsilon} \operatorname{div}(\rho \mathbf{u} e) + \operatorname{div}(\rho \mathbf{u}) = -\frac{1}{\varepsilon} (\rho (\nabla \phi, \mathbf{u}) + \frac{\sigma}{\varepsilon} \rho (\mathbf{u}, \mathbf{u})). \end{cases}$$

• with ϕ the gravity potential, σ the friction coefficient.

Properties :

• Entropy inequality
$$\partial_t \rho S + \frac{1}{\varepsilon} \operatorname{div}(\rho \mathbf{u} S) \ge 0$$
.

Steady-state :

$$\begin{cases} \mathbf{u} = \mathbf{0}, \\ \nabla \boldsymbol{p} = -\rho \nabla \phi. \end{cases}$$

Diffusion limit:

$$\left\{ \begin{array}{l} \partial_t \rho + \operatorname{div}(\rho \mathbf{u}) = \mathbf{0}, \\ \partial_t \rho e + \operatorname{div}(\rho \mathbf{u}e) + \rho \operatorname{div} \mathbf{u} = \mathbf{0}, \\ \mathbf{u} = -\frac{1}{\sigma} \left(\nabla \phi + \frac{1}{\rho} \nabla \rho \right). \end{array} \right.$$



Design of AP nodal scheme I

Idea :

Modify the Lagrange+remap classical scheme with the Jin-Levermore method

Classical Lagrange+remap scheme (LP scheme):

$$\begin{cases} | \Omega_j | \partial_t \rho_j + \frac{1}{\varepsilon} \left(\sum_{R_+} \mathbf{u}_{jr} \rho_j + \sum_{R_-} \mathbf{u}_{jr} \rho_{k(r)} \right) = 0 \\ | \Omega_j | \partial_t \rho_j \mathbf{u}_j + \frac{1}{\varepsilon} \left(\sum_{R_+} \mathbf{u}_{jr} (\rho \mathbf{U})_j + \sum_{R_-} \mathbf{u}_{jr} (\rho \mathbf{U})_{k(r)} + \sum_r \mathbf{pC}_{jr} \right) = 0 \\ | \Omega_j | \partial_t \rho_j + \frac{1}{\varepsilon} \left(\sum_{R_+} \mathbf{u}_{jr} (\rho \mathbf{e})_j + \sum_{R_-} \mathbf{u}_{jr} (\rho \mathbf{e})_{k(r)} + \sum_r (\mathbf{pC}_{jr}, \mathbf{u}_r) \right) = 0 \end{cases}$$

with Lagrangian fluxes

$$\left\{ \begin{array}{l} \mathbf{G}_{jr} = p_j \mathbf{C}_{jr} + \rho_j c_j \hat{\alpha}_{jr} (\mathbf{u}_j - \mathbf{u}_r) \\ \sum_j \rho_j c_j \hat{\alpha}_{jr} \mathbf{u}_r = \sum_j \rho_j \mathbf{C}_{jr} + \sum_j \rho_j c_j \hat{\alpha}_{jr} \mathbf{u}_j \end{array} \right.$$

Advection fluxes: $\mathbf{u}_{jr} = (\mathbf{C}_{jr}, \mathbf{u}_r), R_+ = (r/\mathbf{u}_{jr} > 0), R_- = (r/\mathbf{u}_{jr} < 0)$ et $\rho_{k(r)} = \frac{\sum_{j/\mathbf{u}_{jr} > 0} \mathbf{u}_{jr} \rho_j}{\sum_{j/\mathbf{u}_{jr} > 0} \mathbf{u}_{jr}}.$





Design of AP nodal scheme II

Jin Levermore method:

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Plug the relation $abla p + O(\varepsilon^2) = -\rho \nabla \phi - rac{\sigma}{\varepsilon} \rho \mathbf{U}$ in the Lagrangian fluxes

The modified scheme is given by

$$\begin{cases} \mid \Omega_{j} \mid \partial_{t}\rho_{j} + \frac{1}{\varepsilon} \left(\sum_{\mathcal{R}_{+}} \mathbf{u}_{jr}\rho_{j} + \sum_{\mathcal{R}_{-}} \mathbf{u}_{jr}\rho_{k(r)} \right) = 0 \\ \mid \Omega_{j} \mid \partial_{t}\rho_{j}\mathbf{u}_{j} + \frac{1}{\varepsilon} \left(\sum_{\mathcal{R}_{+}} \mathbf{u}_{jr}(\rho\mathbf{U})_{j} + \sum_{\mathcal{R}_{-}} \mathbf{u}_{jr}(\rho\mathbf{U})_{k(r)} + \sum_{r} \mathbf{pC}_{jr} \right) \\ = -\frac{1}{\varepsilon} \left(\sum_{r} \hat{\beta}_{jr}(\rho\nabla\phi)_{r} + \frac{\sigma}{\varepsilon} \sum_{r} \rho_{r} \hat{\beta}_{jr}\mathbf{u}_{r} \right) \\ \mid \Omega_{j} \mid \partial_{t}\rho_{j} + \frac{1}{\varepsilon} \left(\sum_{\mathcal{R}_{+}} \mathbf{u}_{jr}(\rho\varepsilon)_{j} + \sum_{\mathcal{R}_{-}} \mathbf{u}_{jr}(\rho\varepsilon)_{k(r)} + \sum_{r} (\mathbf{pC}_{jr}, \mathbf{u}_{r}) \right) \\ = -\frac{1}{\varepsilon} \left(\sum_{r} (\hat{\beta}_{jr}(\rho\nabla\phi)_{r}, \mathbf{u}_{r}) + \frac{\sigma}{\varepsilon} \sum_{r} \rho_{r} (\mathbf{u}_{r}, \hat{\beta}_{jr}\mathbf{u}_{r}) \right) \end{cases}$$

with the new Lagrangian fluxes

$$\begin{cases} \mathbf{p}\mathbf{C}_{jr} = \rho_{j}\mathbf{C}_{jr} + \rho_{j}c_{j}\hat{\alpha}_{jr}(\mathbf{u}_{j} - \mathbf{u}_{r}) - \hat{\beta}_{jr}(\rho\nabla\phi)_{r} - \frac{\sigma}{\varepsilon}\rho_{r}\hat{\beta}_{jr}\mathbf{u}_{r} \\ \left(\sum_{j}\rho_{j}c_{j}\hat{\alpha}_{jr} + \frac{\sigma}{\varepsilon}\rho_{r}\sum_{j}\hat{\beta}_{jr}\right)\mathbf{u}_{r} = \sum_{j}\rho_{j}\mathbf{C}_{jr} + \sum_{j}\rho_{j}c_{j}\hat{\alpha}_{jr}\mathbf{u}_{j} - (\sum_{j}\hat{\beta}_{jr})(\rho\nabla\phi)_{r} \end{cases}$$

 \blacksquare and $(\rho \nabla \phi)_r$ a discretization of $\rho \nabla \phi$ at the interface .





Properties

Limit diffusion scheme:

If the local matrices are invertible then the LR-AP scheme tends to the following scheme

$$\begin{cases} |\Omega_{j}| \partial_{t}\rho_{j} + \left(\sum_{R_{+}} \mathbf{u}_{jr}\rho_{j} + \sum_{R_{-}} \mathbf{u}_{jr}\rho_{k(r)}\right) = 0 \\ |\Omega_{j}| \partial_{t}\rho_{j} + \left(\sum_{R_{+}} \mathbf{u}_{jr}(\rho e)_{j} + \sum_{R_{-}} \mathbf{u}_{jr}(\rho e)_{k(r)} + p_{j}\sum_{r}(\mathbf{C}_{jr}, \mathbf{u}_{r})\right) = 0 \\ \sigma\rho_{r}\left(\sum_{j} \hat{\beta}_{jr}\right) \mathbf{u}_{r} = \sum_{j} p_{j}\mathbf{C}_{jr} - \left(\sum_{j} \hat{\beta}_{jr}\right) (\rho\nabla\phi)_{r} \end{cases}$$

- For $p = K\rho$, numerically the scheme converge at the order of the advection scheme.
- Open question: Verify this for a non isothermal pressure law as perfect gas law.

Well balanced property

- We define the discrete gradient $\nabla_r p = -(\sum_j \hat{\beta}_{jr})^{-1} \sum_j p_j \mathbf{C}_{jr}$ and ρ_r an average of ρ_j around \mathbf{x}_r .
- If the initial data are given by the discrete steady-state $\nabla_r p = -(\rho \nabla \phi)_r$, $\rho_j^{n+1} = \rho_j^n$, $\mathbf{u}_j^{n+1} = \mathbf{u}_j^n$ and $e_j^{n+1} = e_j^n$,

Remark: if you initialize your scheme with a continuous steady-state the final space error is given by the consistency error between the continuous and discrete steady-state.



High order reconstruction of steady-state

- Aim: Conserve the stability property of the first order scheme but discretize the steady-state with a high order accuracy or exactly.
- Method : construct high order discrete steady-state
- **1**D discrete steady state: $p_{j+1} p_j = -\Delta x_{j+\frac{1}{2}} (\rho \partial_x \phi)_{j+\frac{1}{2}}$ with $(\rho \partial_x \phi)_{j+\frac{1}{2}} = \frac{1}{2} (\rho_{j+1} + \rho_j) (\phi_{j+1} \phi_j).$

To begin we consider the steady state

$$\partial_x p = -\rho \partial_x \phi$$

we integrate on the dual cell [x_j, x_{j+1}] to obtain

$$\Delta x_{j+\frac{1}{2}} \left(\frac{1}{\Delta x_{j+\frac{1}{2}}} \int_{x_j}^{x_{j+1}} \partial_x \boldsymbol{p}(x) \right) = -\Delta x_{j+\frac{1}{2}} \left(\frac{1}{\Delta x_{j+\frac{1}{2}}} \int_{x_j}^{x_{j+1}} \boldsymbol{\rho}(x) \partial_x \boldsymbol{\phi}(x) \right).$$





High order reconstruction of steady-state

- Aim: Conserve the stability property of the first order scheme but discretize the steady-state with a high order accuracy or exactly.
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• We introduce 3 polynomials $\overline{\rho}_{j+\frac{1}{2}}(x) = \sum_{k=1}^{q} r_k x^k$ et $\overline{p}_{j+\frac{1}{2}}(x) = \sum_{k=1}^{q+1} p_k x^k$, $\overline{\phi}_{j+\frac{1}{2}}(x) = \sum_{k=1}^{q+1} \phi_k x^k$ with

$$\int_{x_{l-\frac{1}{2}}}^{x_{l+\frac{1}{2}}} \overline{\rho}_{j+\frac{1}{2}}(x) = \Delta x_{l} \rho_{l}, \quad \int_{x_{l-\frac{1}{2}}}^{x_{l+\frac{1}{2}}} \overline{\rho}_{j+\frac{1}{2}}(x) = \Delta x_{l} \rho_{l}, \quad \int_{x_{l-\frac{1}{2}}}^{x_{l+\frac{1}{2}}} \overline{\phi}_{j+\frac{1}{2}}(x) = \Delta x_{l} \phi_{l}$$

and $l \in S(j)$ (S(j) a subset of cell around j). Using these polynomials we obtain the new discrete steady-state

$$\Delta x_{j+\frac{1}{2}} \left(\frac{1}{\Delta x_{j+\frac{1}{2}}} \int_{x_j}^{x_{j+1}} \partial_x \overline{p}_{j+\frac{1}{2}}(x) \right) = -\Delta x_{j+\frac{1}{2}} \left(\frac{1}{\Delta x_{j+\frac{1}{2}}} \int_{x_j}^{x_{j+1}} \overline{\rho}_{j+\frac{1}{2}}(x) \partial_x \overline{\phi}_{j+\frac{1}{2}}(x) \right)$$





High order reconstruction of steady-state

- Aim: Conserve the stability property of the first order scheme but discretize the steady-state with a high order accuracy or exactly.
- Method : construct high order discrete steady-state
- To incorporate the discrete steady state in the scheme we need to have a pressure gradient which correspond to the viscosity of the scheme.
- We obtain a q-order steady-state:

$$p_{j+1} - p_j = -\Delta x_{j+\frac{1}{2}} \left(\rho \partial_x \phi\right)_{j+\frac{1}{2}}^{HO}$$

with

$$(\rho g)_{j+\frac{1}{2}}^{HO} = \frac{1}{\Delta x_{j+\frac{1}{2}}} \left(\left(\int_{x_j}^{x_{j+1}} \partial_x \overline{p}_{j+\frac{1}{2}}(x) \right) + \left(\int_{x_j}^{x_{j+1}} \overline{\rho}_{j+\frac{1}{2}}(x) \partial_x \overline{\phi}_{j+\frac{1}{2}}(x) \right) - (p_{j+1} - p_j) \right)$$



High order reconstruction of steady-state

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$$(\rho g)_{j+\frac{1}{2}}^{HO} = \frac{1}{\Delta x_{j+\frac{1}{2}}} \left(\left(\int_{x_j}^{x_{j+1}} \partial_x \overline{\rho}_{j+\frac{1}{2}}(x) \right) + \left(\int_{x_j}^{x_{j+1}} \overline{\rho}_{j+\frac{1}{2}}(x) \partial_x \overline{\phi}_{j+\frac{1}{2}}(x) \right) - (p_{j+1} - p_j) \right)$$

2D extension

The method is the same. Just we use a constant stencil and a least square method to determinate the coefficient of the polynomials



FV nodal schemes

Numerical result : large opacity

- Test case: sod problem with $\sigma > 0$, $\varepsilon = 1$ and $\nabla \phi = 0$.
- σ = 1

AP scheme, ρ

non-AP scheme, ρ





FV nodal schemes

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Numerical result : large opacity

- Test case: sod problem with $\sigma > 0$, $\varepsilon = 1$ and $\nabla \phi = 0$.
- $\sigma = 10^{6}$

AP scheme, ρ non-AP scheme, ρ 0.6 0.5 0.4 0.3 0.2 0.1 AP scheme, ϵ non-AP scheme, ϵ 2.4 2.3 2.2 2.1 2 1.9 1.9 0.4



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Result for steady-state

Steady-state: $\rho(t, x) = 3 + 2\sin(2\pi x), u(t, x) = 0$

■ $p(t, x) = 3 + 3\sin(2\pi x) - \frac{1}{2}\cos(4\pi x)$ and $\phi(x) = -\sin(2\pi x)$. Random mesh.

Schemes	LR	R LR-AP (2)		LR-AP (3)		LR-AP (4)		
cells	Err	q	Err	q	Err	q	Err	q
20	0.8335	-	0.0102	-	0.0079	-	0.0067	-
40	0.4010	1.05	0.0027	1.91	8.4E-4	3.23	1.5E-4	5.48
80	0.2065	0.96	7.0E-4	1.95	7.7E-5	3.45	4.1E-6	5.19
160	0.1014	1.02	1.7E-4	2.04	7.0E-6	3.46	1.0E-7	5.36

Steady-state: $\rho(t, x) = e^{-gx}$, u(t, x) = 0, $p(t, x) = e^{-gx}$ et $\phi = gx$. Random mesh

Schemes	LR	LR LR-AP (2)		LR-AP (3)		LR-AP (4)		
cells	Err	q	Err	q	Err	q	Err	q
20	0.0280	-	6.5E-4	-	1.8E-5	-	8.0E-7	-
40	0.0152	0.88	1.4E-4	2.21	2.0E-6	3.17	3.8E-8	4.4
80	0.0072	1.08	3.3E-5	2.08	2.0E-7	3.32	2.0E-9	4.25
160	0.0038	0.92	8.8E-6	1.90	2.8E-8	2.84	1.1E-10	4.18



Conclusion and perspectives

- Conclusion
 - \square *P*₁ **model**: First AP scheme (time and space) on unstructured meshes (now other schemes have been developed).
 - \square *P*₁ model: Uniform proof of convergence on unstructured meshes in 1D and 2D.
 - $\hfill\square$ AP schemes for general linear systems with source terms using previous schemes and "micro-macro" method.
 - □ **Euler model with external force** AP schemes with a new high order reconstruction of the steady states
 - □ **Problem for all the schemes** : spurious mods in few cases (example: Cartesian mesh + Dirac Initial data).
 - Possible perspectives
 - \square P_1 model: Theoretical study of the explicit and semi implicit scheme.
 - Euler model: Entropy study for scheme.
 - □ Find a generic procedure to stabilize the nodal scheme (exist for the Lagrangian nodal scheme for the Euler equations).



Thanks

Thank you



