Boundary elements for contact problems: Stabilization, hp-methods, dynamics

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This talk considers recent work on boundary elements for the approximation of frictional contact problems. It focuses on stabilized hp-adaptive methods [1], as well as on first results for dynamic contact [2]. Boundary elements formulate the Signorini problem, possibly with friction, as a variational inequality for the Dirichlet-to-Neumann operator on the boundary. The resulting problem is then discretized and

solved in a saddle point formulation. As a basic problem of high-order polynomial ansatz functions, the discretized systems degenerate as the polynomial degree tends to infinity. We show that a basic idea by Barbosa and Hughes for the stabilization of finite element methods can be extended to boundary elements and obtain a priori and a posteriori error estimates for Tresca friction. Numerical experiments in 2d confirm the theoretical results and apply the approach to contact problems with Coulomb friction.

We then present first results with low-order ansatz functions for a dynamic contact problem for the wave equation. A priori estimates are obtained for Galerkin approximations in the case of a flat contact area, where the existence of solutions to the continuous problem is known. Numerical experiments in 3d demonstrate the performance of the proposed method. They indicate the stability and convergence beyond flat geometries. Future work will focus on space-time stabilization and adaptively generated meshes [3, 4].

Références

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